



Action TU1208 Civil Engineering Applications of Ground Penetrating Radar

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Design and realisation of a cheap GPR for educational purposes

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Talk Layout

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- Basic principles
- Guide > RF Hardware design
 - Software and Firmware to manage the microcontroller
 - Basic software for interpreting the output signal
- Conclusions
- References
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Motivation of the project

and participating teams



One of the main objectives of the COST Action TU1208 is to foster a wider use of the GPR technique in Europe and beyond.

The dissemination of GPR technology concepts should be a starting point for introducing young people to the GPR technique.

Moreover, the availability of a detailled guide to build a cheap GPR prototype will allow several researchers and students to realize their own equipment, whenever they cannot afford to buy a commercial one.

The inspiration for this project was a radar prototype by Lincoln Laboratory at Massachusetts Institute of Technology (MIT) [6], but we worked at increasing the performance and interactivity of the MIT device, as well as on adapting it to the GPR case.



Motivation

We hope that our project will facilitate the introduction of the GPR technique into the educational process in many Countries.

This presentation is an excerpt of a longer document that we prepared, which aims at explaining how to design and realize a frequencymodulated continuous-wave (FCMW) GPR, with detailled information for the step by step construction phases, schemes, software codes, and all the necessary documentation to independently build a GPR prototype.

The guide that we wrote aims at enhancing the overall technical literacy of students, enabling them to develop their own radar by using minimum prerequisite knowledge about radar systems.



Teams participating in the project

project phase	Laboratory
 RF electronic hardware design. DC power source design.	Electronics for the Environment Laboratory – Dep. of Information Eng., Electronics and Telecommunications (DIET) – Sapienza University of Rome
 Software development for implementing firmware into microcontrollers. Software development for managing device by PC. 	Remote Sensing Laboratory Bauman Moscow State Technical University & Electronics for the Environment Laboratory - DIET – Sapienza University of Rome
 Software development for interpreting the GPR signal detection. 	Electronics for the Environment Laboratory - DIET – Sapienza University of Rome





Basic principles



Basic principles

This guide aims to describe the steps for building a GPR with the main following features:

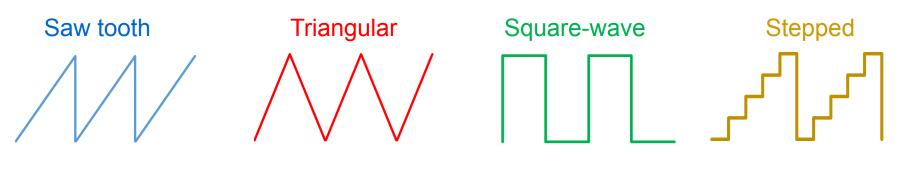
- FMCW radar type
- Use of modular subsystems that allow you to replace components for implementing design alternatives, and get greater understanding in the case of educational activity
- Device managed by PC for interactive control of GPR
- Frequency sweep: f_{min}=1.3 GHz, f_{max}=2.6 GHz
- Choice of smaller interval for frequencies of use
- Choice of modulation wave shape
- Choice of modulating wave period
- COTS (components off-the-shelf)
- Low cost

Basic principles Essential characteristics

FMCW radar working is based on the continuous emission of sinusoidal waveform (CW), which frequency is suitably modulated (FM). So, a basic design of a FMCW radar includes the following characteristics:

- The adoption of a local oscillator (LO).
- The received signal, properly amplified, is mixed with LO to create beat.
- The frequency of beat signal is proportional to the distance between the detected object and radar.

By including VCO device as LO, we can carry out different frequency modulations by changing voltage control waveform:

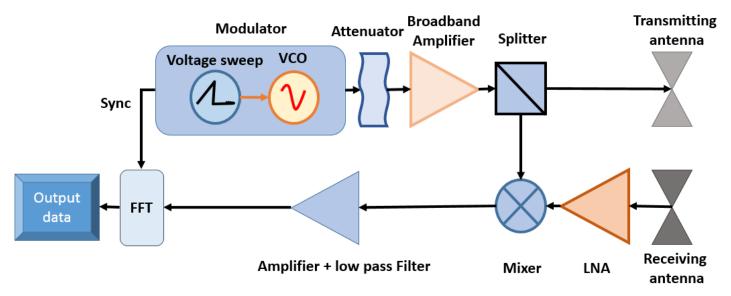


Basic principles Signal processing

FFT

The application of the Fast Fourier Transform to the output signal allows to obtain frequency data, and consequently to calculate the distance of multiple detected objects.

The use of a low pass filter increases the signal to noise ratio, decreasing broadband high frequency noise.



FFT and Output data blocks are carried out inside the PC



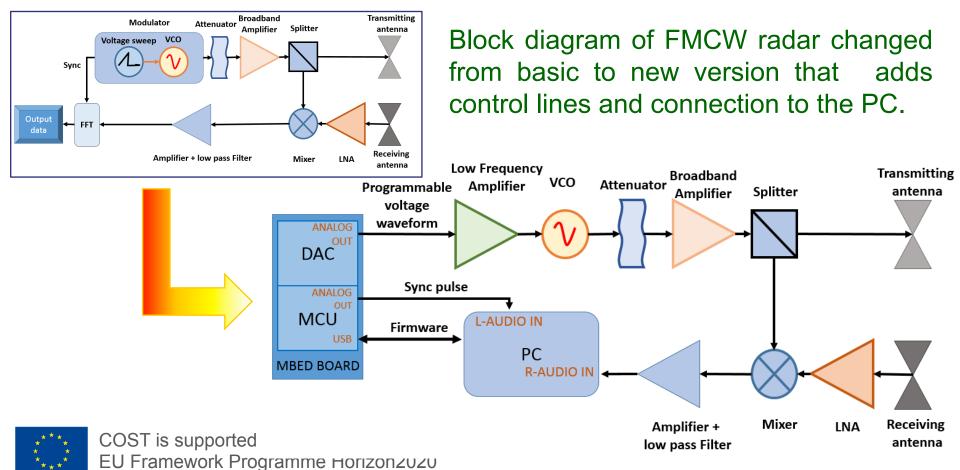


Guide

RF Hardware design



In order to increase interactive features and versatility of modulation shapes, we replaced the analog function generator with a versatile Mbed LPC1768 microcontroller (MCU) board, with high performance ARM Cortex-M3 core.





Bill of materials together with pdf datasheet of more important devices

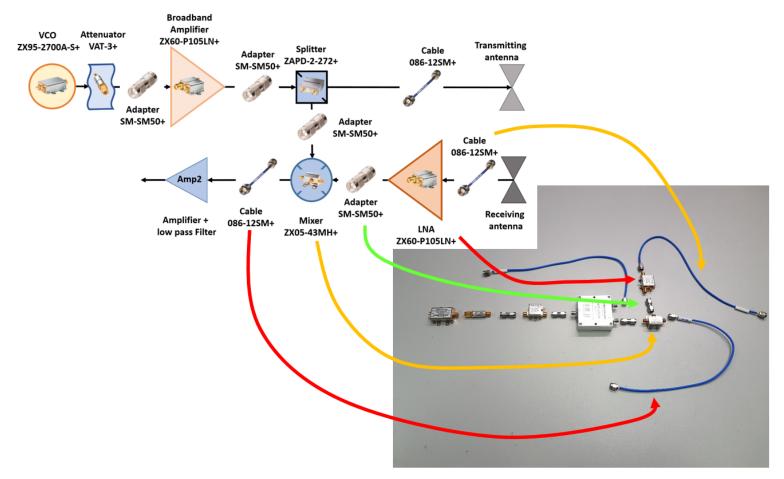
Part number Qty Description Manufacturer datasheet Approximate cost (E) Bill of material – Amplifier+ Low pass filter (Amp2) subsystem. ZX95-2700A-S+ 1 Voltage Controlled Oscil Part number Qt Description Manufacturer datasheet Approximate Band 1300 to 2700 MHz cost (€) v VAT-3+ SMA Fixed Attenuator 5 1 Bill of material – Low frequency amplifier subsystem (Amp1). δP Analog Device OP467.pdf 16.04 Part number Description Manufacturer Qty datasheet Approximate cost (€) Vishay 0.085 LT1077fa.pdf 2.61 LT1077S8#PBF Micropower, Single Supply, 1 Linear Precision Op Amp (U1) Technology Bill of material - mbed board Bill of material – Power supply subsystem (DC-DC converters). W t number Qty Description Manufactu datasheet Approximat Part number Qt Description Manufacturer datasheet Approx. e cost (€) rer cost (€) LPC1768.pdf, ER TSRN 1-2465 2 DC/DC converter 6.5V 1° (U2,U3) Traco Power TSRN-1 DC DC 12.08 x 2 ARM mbed LPC1768 prototyping mbed-005.1.pdf, converter.pdf)-LPC1768 1 board (MBED) mbed lpc17xx_um.pdf, 58.23 78E5.0-0.5 1 CONV DC/DC 5V 500MA OUT THRU Recom Power -78Exx-0.5 DC_DC 2.24 lpc17xx_ds.pdf, CR (U1) converter.pdf pc17xx_es.pdf, KE. 4 Position Wire to Board Terminal Buchanan - TE 2 Position Wire to Board Terminal TE 282834-4 Block Horizontal with Board 0.100" Connectivity 1.67 x 2 34-2 3 Block Horizontal with Board 0.100" Connectivit 0.8 x3 (2.54mm) Through Hole (P1, 28 (2.54mm) Through Hole (P1,P2,P3) y AMP VinDC+VnSHDN+Gnd+Vout) Connectors 447687 (supplier: FullPower - Battery Lipo 4S Full Power 25,90 1 Jonathan ®) 2200mAh 35C Silver V2 - DEANS 3-020-10-2 20P single row (female) lo profile SKT Mill-Max 1.86 x 2 (BT1) 00 long ins Multilayer Ceramic Capacitor (MLCC) C0603X103F5JACTU Standard 10000pF, ± 5%, 50 V DC, KEMET 0.52 x 2 2 SMD (C1,C2) 2 Position Wire to Board Terminal TE 282834-2 Block Horizontal with Board 0.100" Connectivity 0.8 (2.54mm) Through Hole (BT1) AMP

Bill of material – RF subsystem.





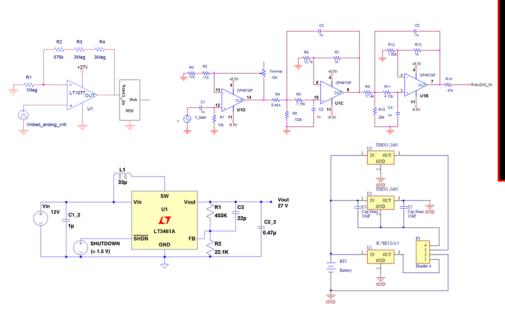
Identification and assembly of RF components

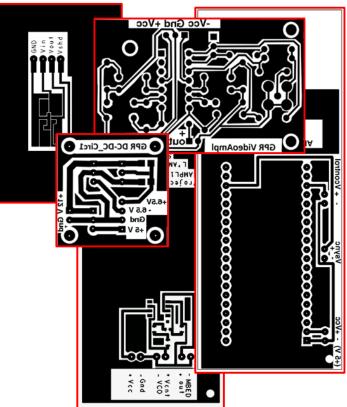






Schematics and PCBs (printed circuit board) together with picture files for reproducing them.

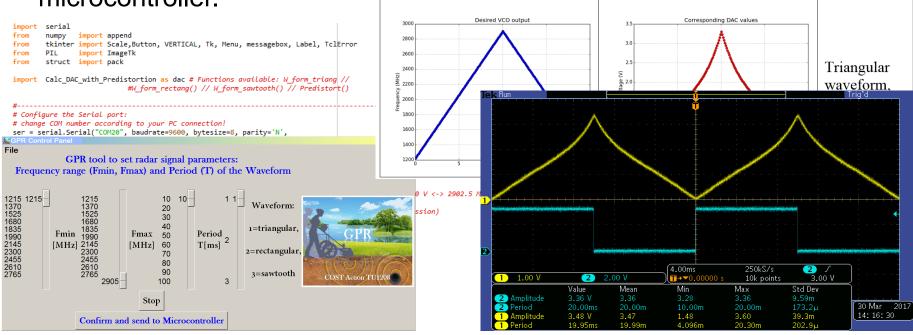








Detailed exposition of developed software codes. Specifically, it includes the firmware program providing control functionalities of the Mbed microcontroller, and the software program for building a graphical interface that provides an easy to use workspace, the user can switch many parameters to control the radar system and send it to the microcontroller.





Suggestions and basic software for interpreting output signal.

0	GPR_FMCV	_ 🗆 🗙
Audio port Time window (sec) 5 Sampling rate (Hz) 44100 (8000, 11025, 44100,48000 e 96000) 44100 Nr of Channels 2 Nr of bits 2 (8, 16 o 24) 24	FMCW Radar Radar Caracteristics of the medium Lower limit of frequency sweep (MHz) 315 Higher limit of frequency sweep (MHz) 536 Sweeping amplitude (MHz) 221	Limits range res. (m) 0.67873 Maximum range 74.8303 detectable
Elapsed time (sec) 85 Graph of the last :5 sec 4.5 4.5 4.5 4.5 4.5 4.5 4.5 4.5 4.5 4.5	econds 40 50 60 70 10 10 10 10 10 10 10 10	Distance calculation Speed calculation PAUSE





Conclusions



Conclusions

- A full guide for designing and realizing an open-source low-cost GPR radar for educational purposes is available on-line.
- Hardware, firmware and software design and implementation are available with full explanation of the details, practical operational suggestions and comments on the entire code.
- The developed software and firmware programs allow interactive control of the GPR functioning, the implemented GUI program is user-friendly and will facilitate students' interaction with the radar system.

Conclusions

- The total price of the radar does not exceed 600 euros, however it can be further reduced with the use of cheaper smd RF component, but in this case it is necessary to use a more complex multilayer pcb. Anyway, the actual version of the radar is the most easy-to-learn and easy-to-built possible.
- Moreover, reducing the bandwidth of the frequency sweep, the price can be cut to 400 euros.
- Future work will include the design and realization of optimized antennas and proper radar kit form-factor.



References

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[2] Tkinter package: <u>https://docs.python.org/2/library/tkinter.html</u>

- [3] V. Ferrara, F. Frezza, F. Mangini, E. Piuzzi, P. Simeoni, N. Tedeschi, Design and realization of a cheap GPR prototype & Recent advancements in forward--scattering methods, COST Action TU1208, 4th General Meeting, Athens, Greece, October19--20, 2015
- [4] V. Ferrara, F. Troiani, F. Frezza, F. Mangini, L. Pajewski, P. Simeoni, N.Tedeschi, Design and Realization of a Cheap Ground Penetrating Radar Prototype @ 2.45 GHz," IEEE Browse Conference Publications -2016 10th European Conference on Antennas and Propagation (EuCAP), Davos, Switzerland, 10-15 April 2016, pp. 1-4, DOI: 10.1109/ EuCAP.2016.7482008

[5] La. Pajewski, R. Persico, V. Ferrara, S. Chicarella, F. Frezza, F. Troiani, COST is supported by the GroundewBienetrating Radar₂₀ prototypes developed in COST Action

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[5] La. Pajewski, R. Persico, V. Ferrara, S. Chicarella, F. Frezza, F. Troiani, "Ground Penetrating Radar prototypes developed in COST Action TU1208, "In the proceedings of 24th International Conference on Software, Telecommunications and Computer Networks (SoftCOM 2016), 2016, Split, Croatia September 22-24, 2016.

[6] Gregory Charvat, Jonathan Williams, Alan Fenn, Steve Kogon, and Jeffrey Herd. RES.LL-003 Build a Small Radar System Capable of Sensing Range, Doppler, and Synthetic Aperture Radar Imaging. January IAP 2011. Massachusetts Institute of Technology: MIT OpenCourseWare, https://ocw.mit.edu. License: Creative Commons BY-NC-SA.

[7] Mbed DAC course-notes: https://developer.mbed.org/media/uploads/ robt/mbed_course_notes_-_analog_input_and_output.pdf



Authors

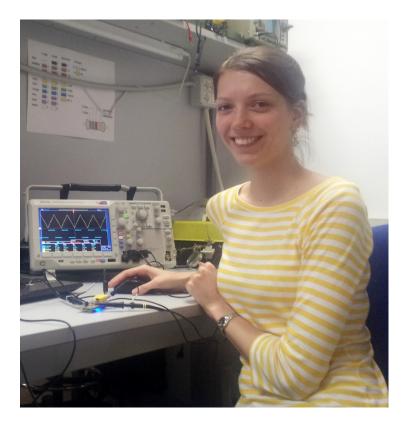


Vincenzo Ferrara received the "Laurea" degree cum laude in Electronic Engineering in March 1980 from "La Sapienza" University of Rome. He joined the Department DIET of the same University, as Associate Professor of Electronic since 2001, and he is scientific responsible of Electronics for the Environment Lab of the DIET.

The scientific research conducted in the years after graduation concerns different topics: electronic systems for the environment, systems for the planning, design and management of broadcasting, geo-referenced detection and software models, application of new technologies for planning and sustainable development, satellite navigation, WSN low power low voltage, energy harvesting, design of RF circuits, LCD, porous silicon. Co-leader in the COST Action TU1208 Project 4.2 of first year of COST action: Advanced application of GPR to the localization and vital signs detection of buried and trapped people. Member of international scientific advisory committee of many conferences, as: Risk analysis, Sustainable Planning & Development, Brownfield, Disaster Management. TCP member of 2nd International workshop on collaborations in ERDM, 2014. (For more info, please visit https:// sites.google.com/a/uniroma1.it/vincenzoferrara-eng/home).



Authors



Margarita Chizh is a PhD student at Bauman Moscow State Technical University. Her primary area of research is microwave imaging, focusing on radar signal processing and radar systems development. She is also a junior researcher at the Remote sensing laboratory which develops and produces holographic subsurface radars for various applications (For more info, please visit http://www.rslab.ru/english/).



Authors

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