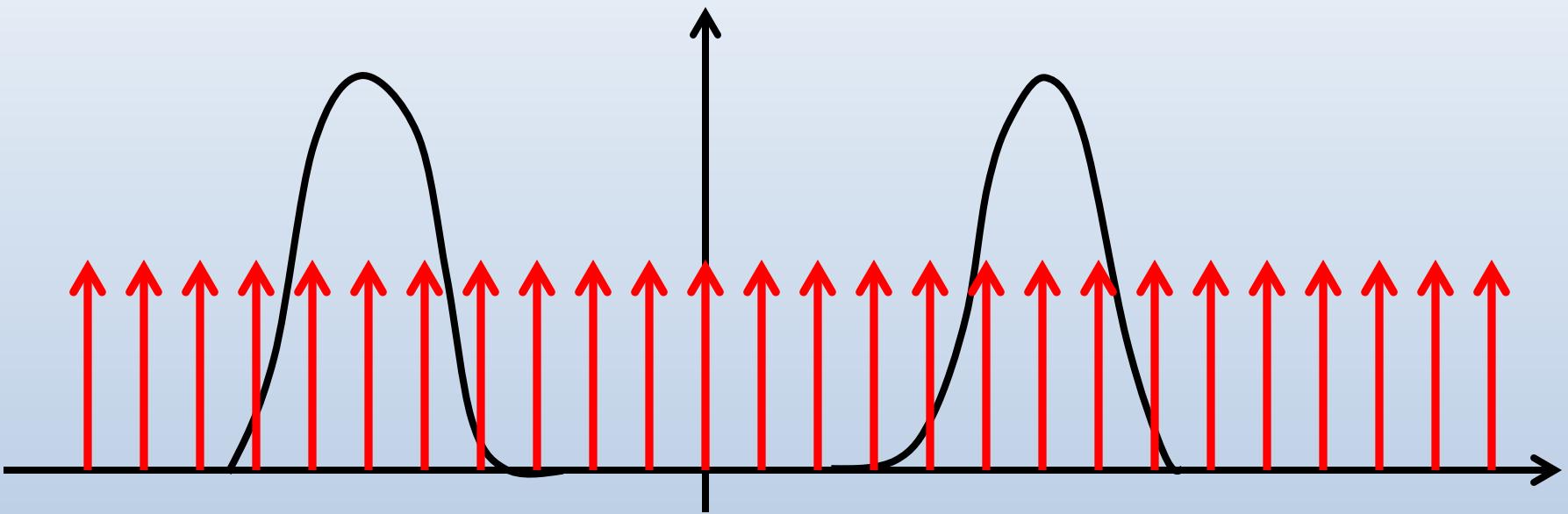


# Reconfigurable stepped-frequency GPR prototype for civil-engineering and archaeological prospection, developed at the National Research Council of Italy. Examples of application and case studies.

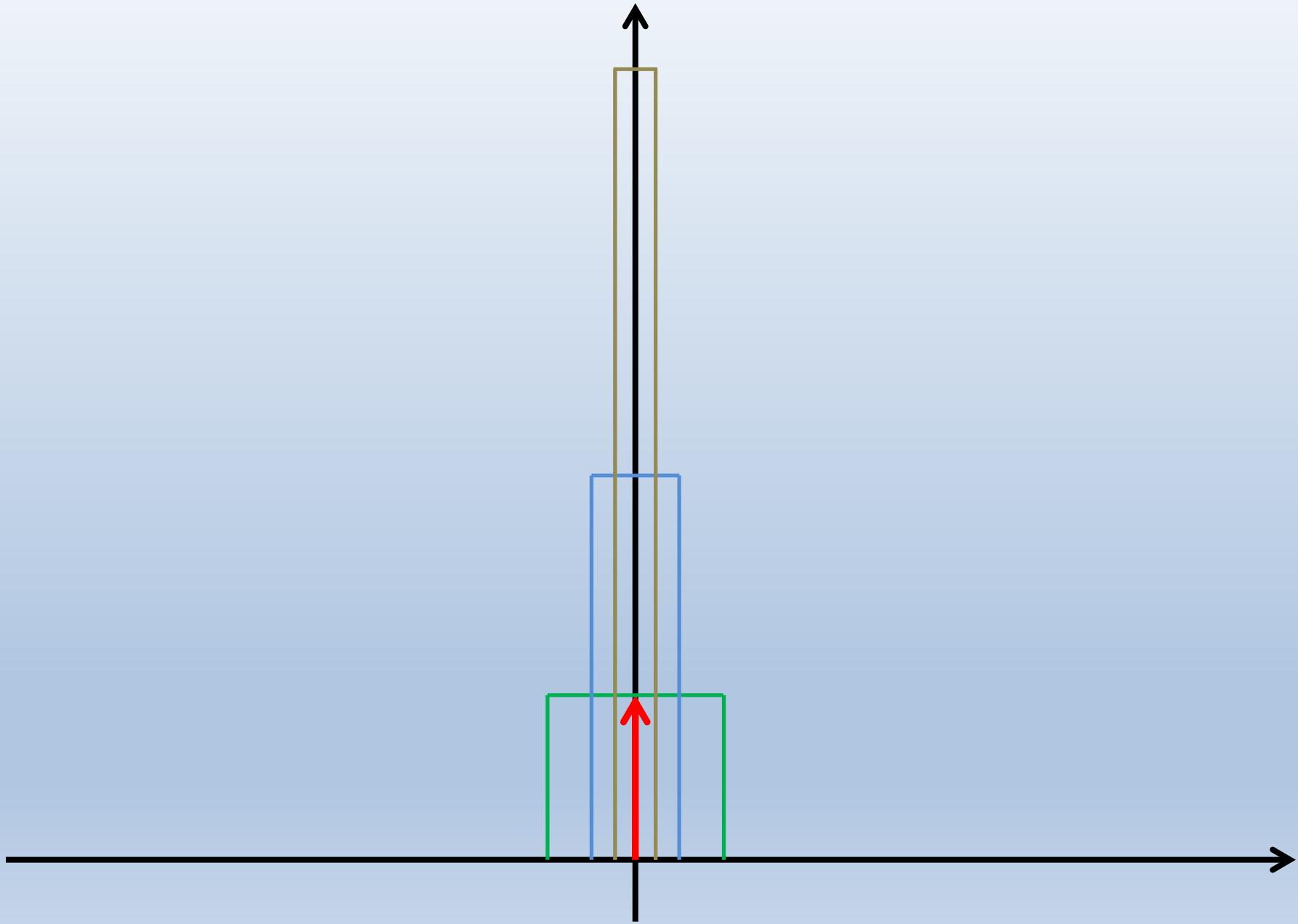
Raffaele Persico



# Stepped frequency: underlying concepts



# The delta function



# Reminds

$$S(f) = \int_{-\infty}^{+\infty} s(t) \exp(-j2\pi ft) dt$$

$$S(-f) = \int_{-\infty}^{+\infty} s(t) \exp(j2\pi ft) dt = S^*(f)$$

$$s(t) = \int_{-\infty}^{+\infty} S(f) \exp(j2\pi ft) df =$$

$$= 2 \operatorname{Re} \int_0^{+\infty} S(f) \exp(j2\pi ft) df$$

# Reminds

## ***Convolution***

$$f_1 * f_2 = g(t) = \int_{-\infty}^{+\infty} f_1(\tau) f_2(t - \tau) d\tau$$

## ***Convolution and Fourier Transform***

$$FT(g_1 * g_2) = G_1(f)G_2(f)$$

$$FT(g_1 g_2) = G_1 * G_2$$

# Reminds

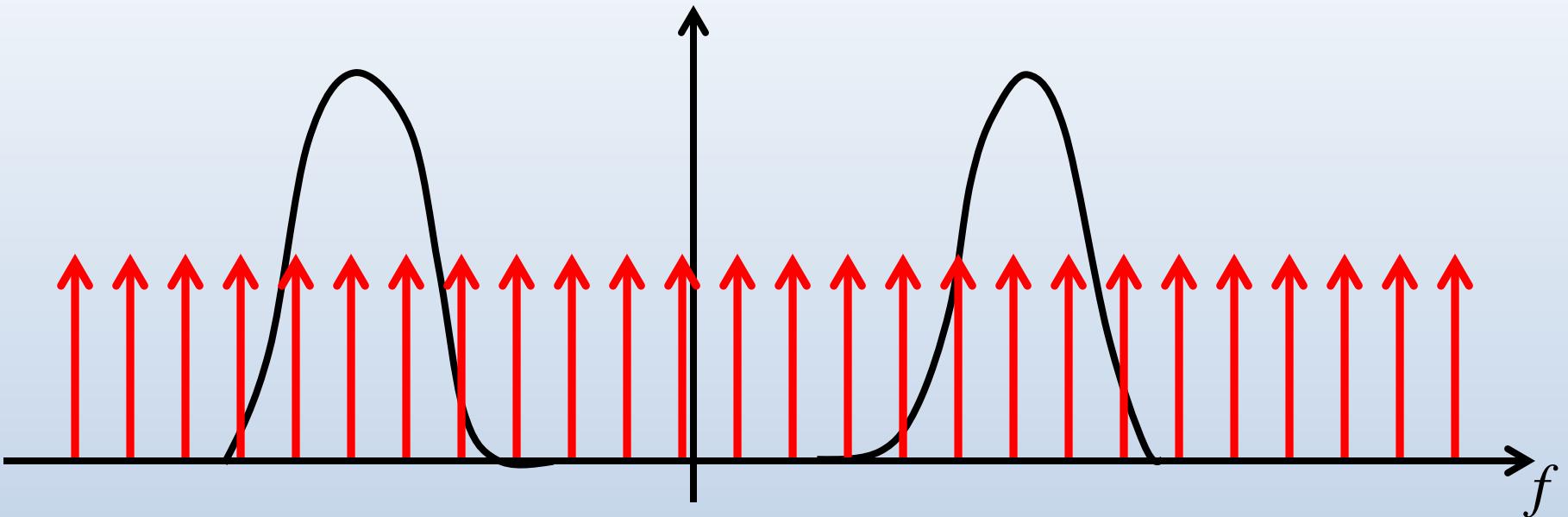
*Sampling property of the delta*

$$\int_{-\infty}^{+\infty} \delta(\tau) f(\tau) d\tau = f(0)$$

$$\int_{-\infty}^{+\infty} \delta(\tau - \tau_o) f(\tau) d\tau = f(\tau_o)$$

$$f * \delta = \int_{-\infty}^{+\infty} f(\tau) \delta(t - \tau) d\tau = f(t)$$

# Ideal sampling of the spectrum



$$\begin{aligned}
 & 2 \operatorname{Re} \int_0^{+\infty} S(f) \exp(j2\pi ft) \left[ \sum_{n=-\infty}^{+\infty} \delta(f - f_o + n\Delta f) \right] df = \\
 & = 2 \operatorname{Re} \left\{ \sum_{n=1}^N S(f_o + n\Delta f) \exp(j2\pi(f_o + n\Delta f)t) \right\} = \\
 & = 2 \sum_{n=1}^N \left[ \operatorname{Re} S(f_o + n\Delta f) \cos(2\pi(f_o + n\Delta f)t) - \operatorname{Im} S(f_o + n\Delta f) \sin(2\pi(f_o + n\Delta f)t) \right] = \\
 & = 2 \sum_{n=1}^N |S(f_o + n\Delta f)| \cos[2\pi(f_o + n\Delta f)t + \angle S(f_o + n\Delta f)]
 \end{aligned}$$

# Expression of the received synthetic pulse for $2N+1$ samples, constant radiated spectrum, constant attenuation and phase of the reflected signals

$$s(t) \approx 2\Delta f \frac{\sin((2N+1)\pi\Delta ft)}{\sin(\pi\Delta ft)} \cos(2\pi f_c t + \theta)$$

*The synthetic pulse is replicated, but the replicas are in general not equal to each other*

# Flux diagram

A sequence of sinusoids is transmitted

$$\cos(2\pi f_n t) = \cos(2\pi(f_{\min} + n\Delta f)t)$$



A sequence of sinusoids is retrieved

$$A_n \cos(2\pi f_n t + \varphi_n) = A_n \cos(2\pi(f_{\min} + n\Delta f)t + \varphi_n)$$

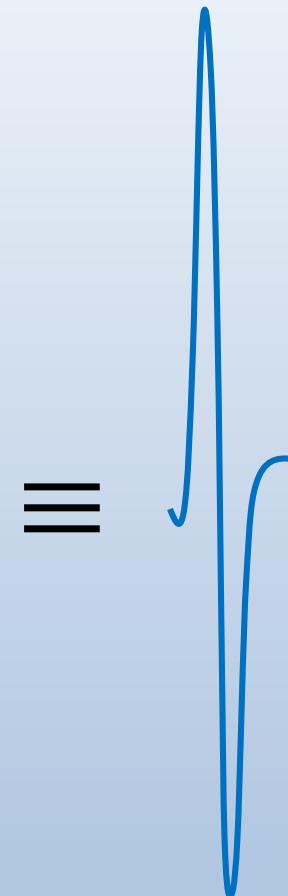
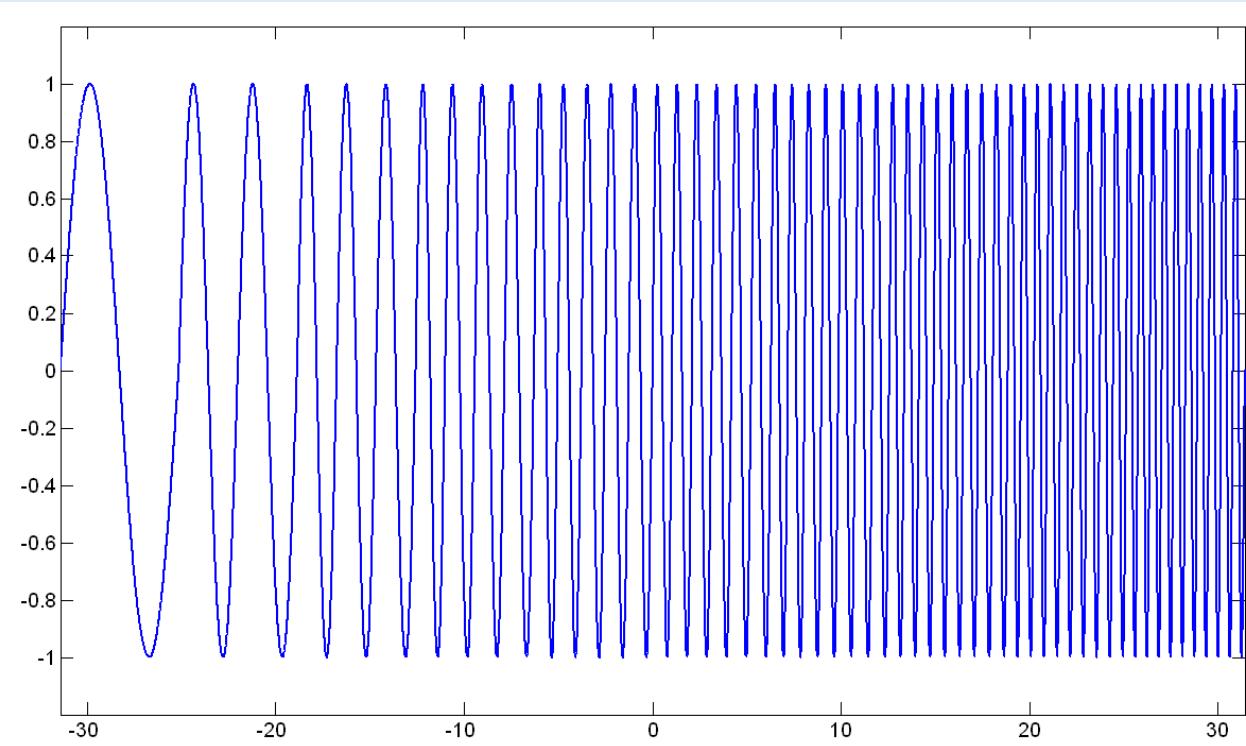


Amplitude and phase  $A_n$  and  $\varphi_n$  are extracted



The received harmonics are summed

# In “synthesis”...



*...but the pulse is replicated with pseudo-replicas  
at distance  $1/\Delta f$  ...*

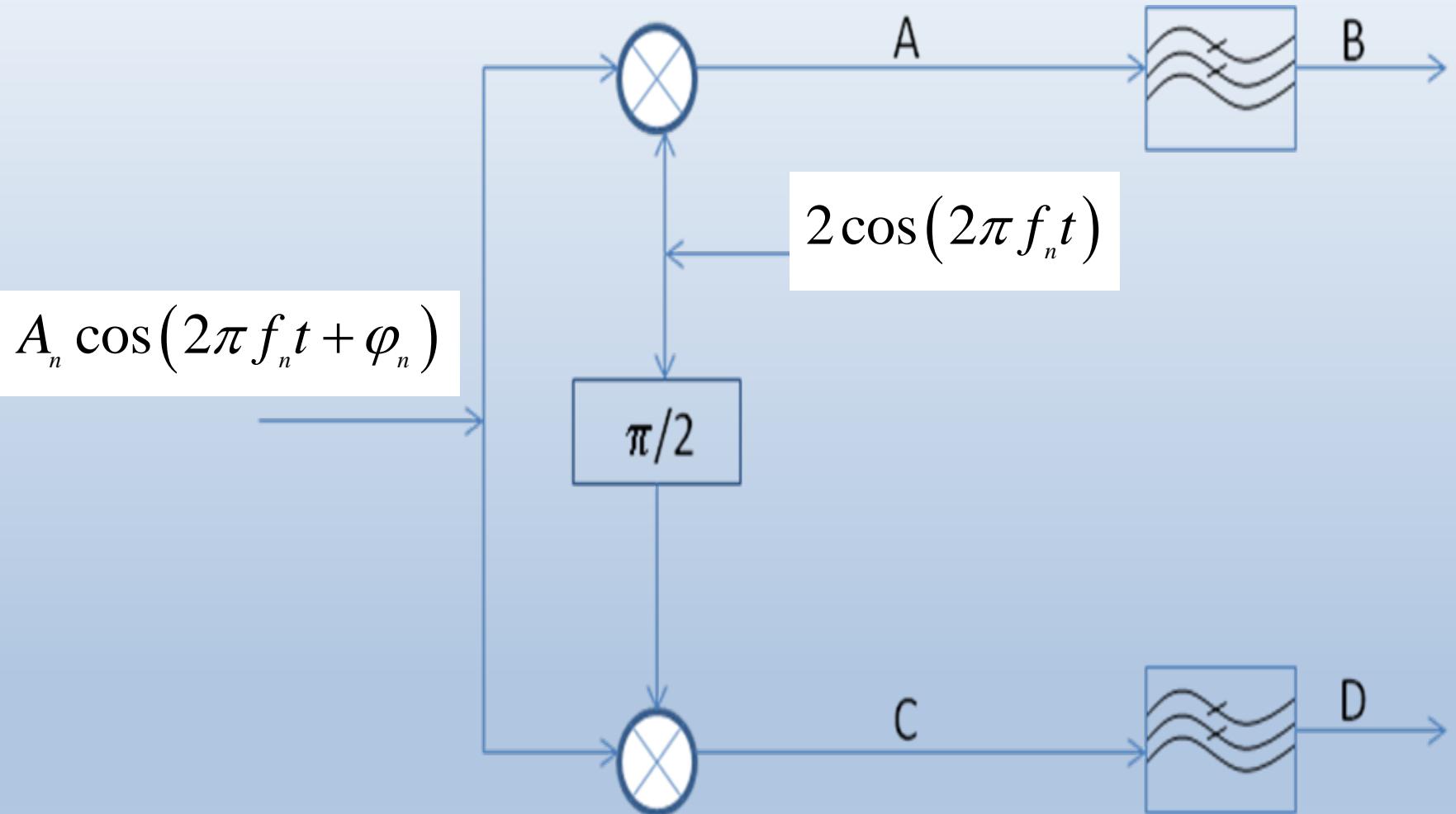
# Trigonometric reminds

$$\cos^2(a) = \frac{1}{2} + \frac{1}{2}\cos(2a)$$

$$\sin^2(a) = \frac{1}{2} - \frac{1}{2}\cos(2a)$$

$$\sin(a)\cos(a) = \frac{1}{2}\sin(2a)$$

# Homodyne demodulation



# Upper branch (in phase component)

$$\begin{aligned} & 2A_n \cos(2\pi f_n t + \varphi_n) \cos(2\pi f_n t) = \\ & = 2A_n \cos(2\pi f_n t) [\cos(2\pi f_n t) \cos(\varphi_n) - \sin(2\pi f_n t) \sin(\varphi_n)] = \\ & = 2A_n \cos(\varphi_n) \cos^2(2\pi f_n t) - 2A_n \sin(2\pi f_n t) \cos(2\pi f_n t) \sin(\varphi_n) = \\ & = 2A_n \cos(\varphi_n) \left[ \frac{1}{2} + \frac{1}{2} \cos(4\pi f_n t) \right] - A_n \sin(\varphi_n) \sin(4\pi f_n t) \Rightarrow \\ & \text{after filtering we achieve } A_n \cos(\varphi_n) = I_n \end{aligned}$$

# Lower branch (quadrature component)

$$\begin{aligned} & 2A_n \cos(2\pi f_n t + \varphi_n) \sin(2\pi f_n t) = \\ & = 2A_n \sin(2\pi f_n t) [\cos(2\pi f_n t) \cos(\varphi_n) - \sin(2\pi f_n t) \sin(\varphi_n)] = \\ & = A_n \cos(\varphi) \sin(4\pi f_n t) - 2A_n \sin^2(2\pi f_n t) \sin(\varphi_n) = \\ & = A_n \cos(\varphi_n) \sin(4\pi f_n t) - 2A_n \left[ \frac{1}{2} - \frac{1}{2} \cos(4\pi f_n t) \right] \sin(\varphi_n) \Rightarrow \\ & \text{after filtering we achieve } -A_n \sin(\varphi) = Q_n \end{aligned}$$

# Final result for each harmonic signal

$$h_n(t) = I_n \cos(2\pi f_n t) + Q_n \sin(2\pi f_n t) = \\ = A_n \cos(2\pi f_n t + \varphi_n)$$

**Synthetic pulse**

$$s(t) = \sum_{n=1}^N h_n(t)$$

# Drawbacks of the homodyne demodulation

*The baseband signal is subject to more noise, in particular the flicker noise, approximately decreasing as  $1/f$  or as a roof function.*

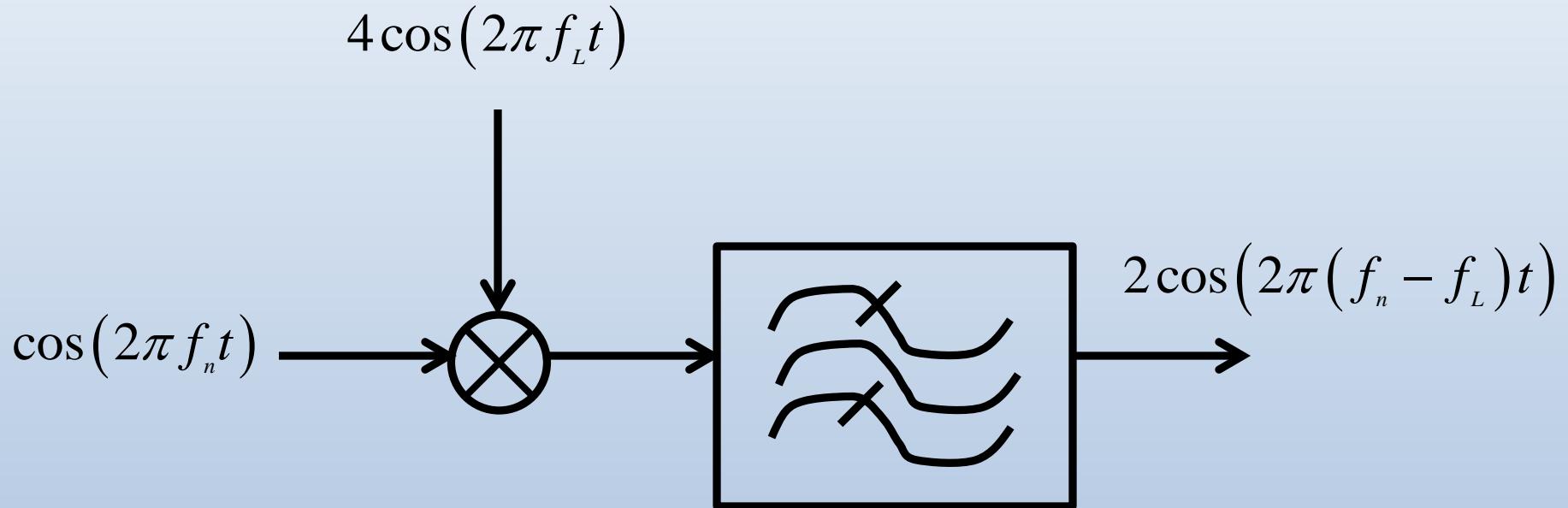
***It is difficult to translate in baseband  $N$  signals from  $N$  different frequencies keeping uniformly low the noise.***

*For this reason it usually preferred an heterodyne demodulation scheme.*

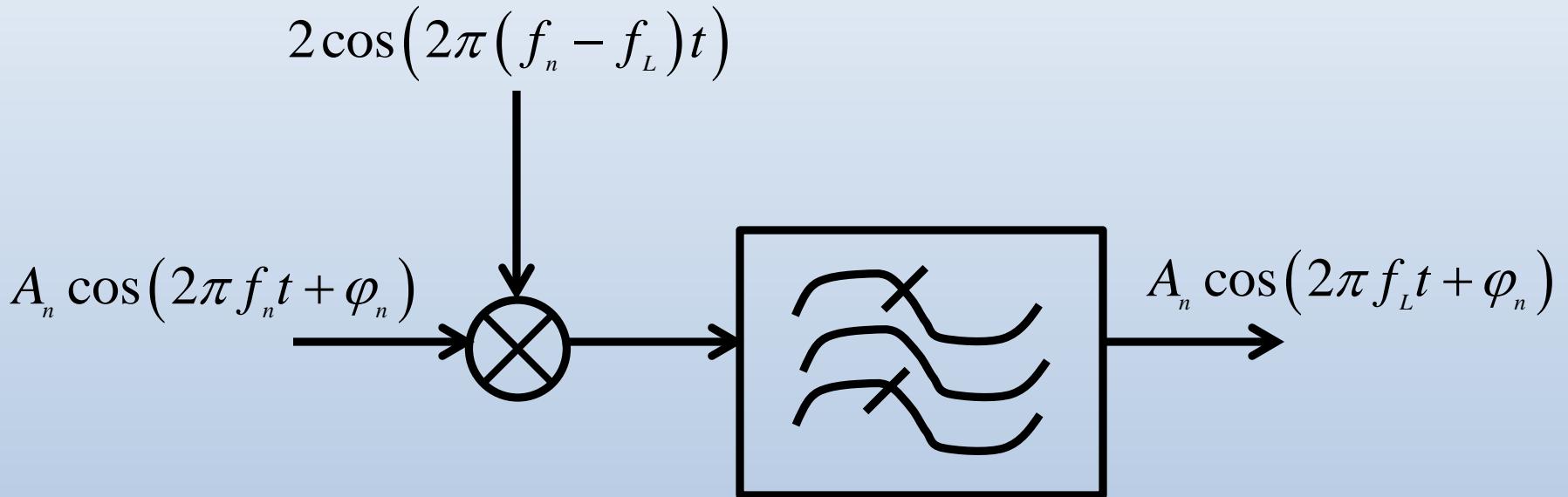
# Trigonometric reminds

$$\begin{cases} 2\cos(a)\cos(b) = \cos(a+b) + \cos(a-b) \\ 2\sin(a)\cos(b) = \sin(a+b) + \sin(a-b) \end{cases}$$

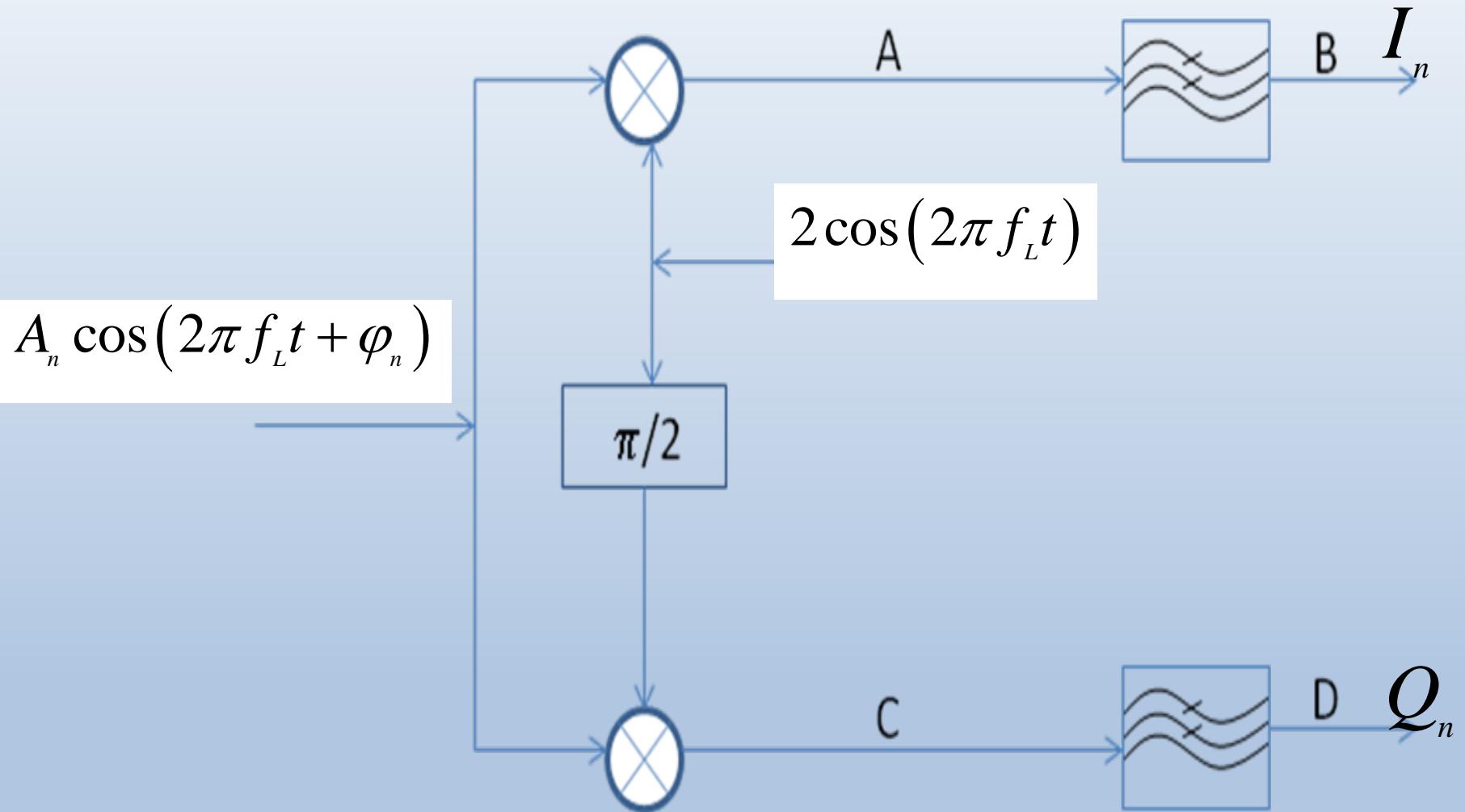
# Translation of the radiated signal on the frequency axis



# Translation of the received signal on the frequency axis



# Heterodyne demodulation



# Averaged measurement of the in-phase and quadrature components

$$\left\{ \begin{array}{l} I_m = \frac{I_{1m} + I_{2m} + \dots + I_{Nm}}{N} \\ Q_m = \frac{Q_{1m} + Q_{2m} + \dots + Q_{Nm}}{N} \end{array} \right.$$

(N is chosen by the manufacturer)

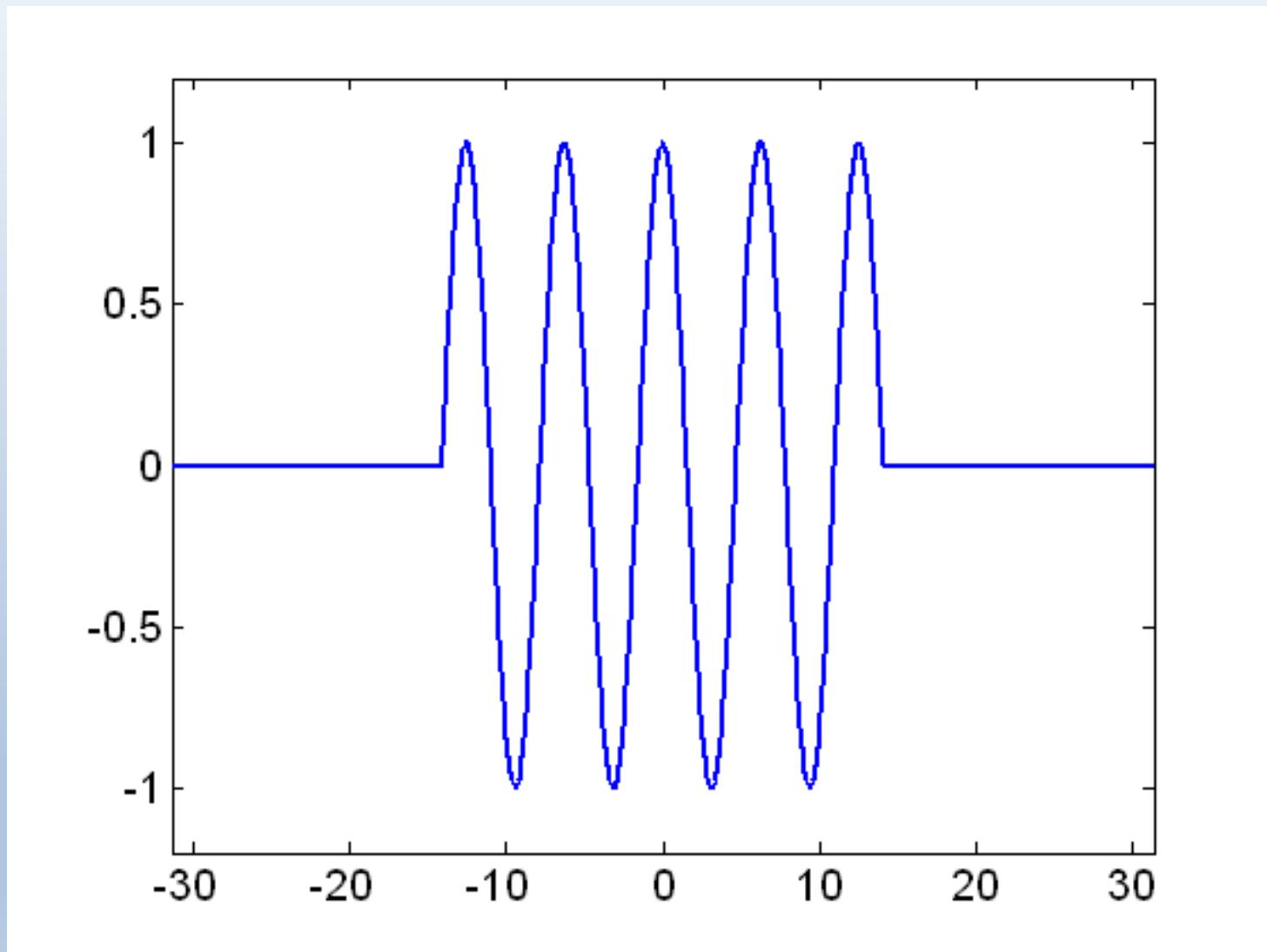
# Power of the noise (white noise) on each received “harmonic” signal

$$N = K_B T B$$

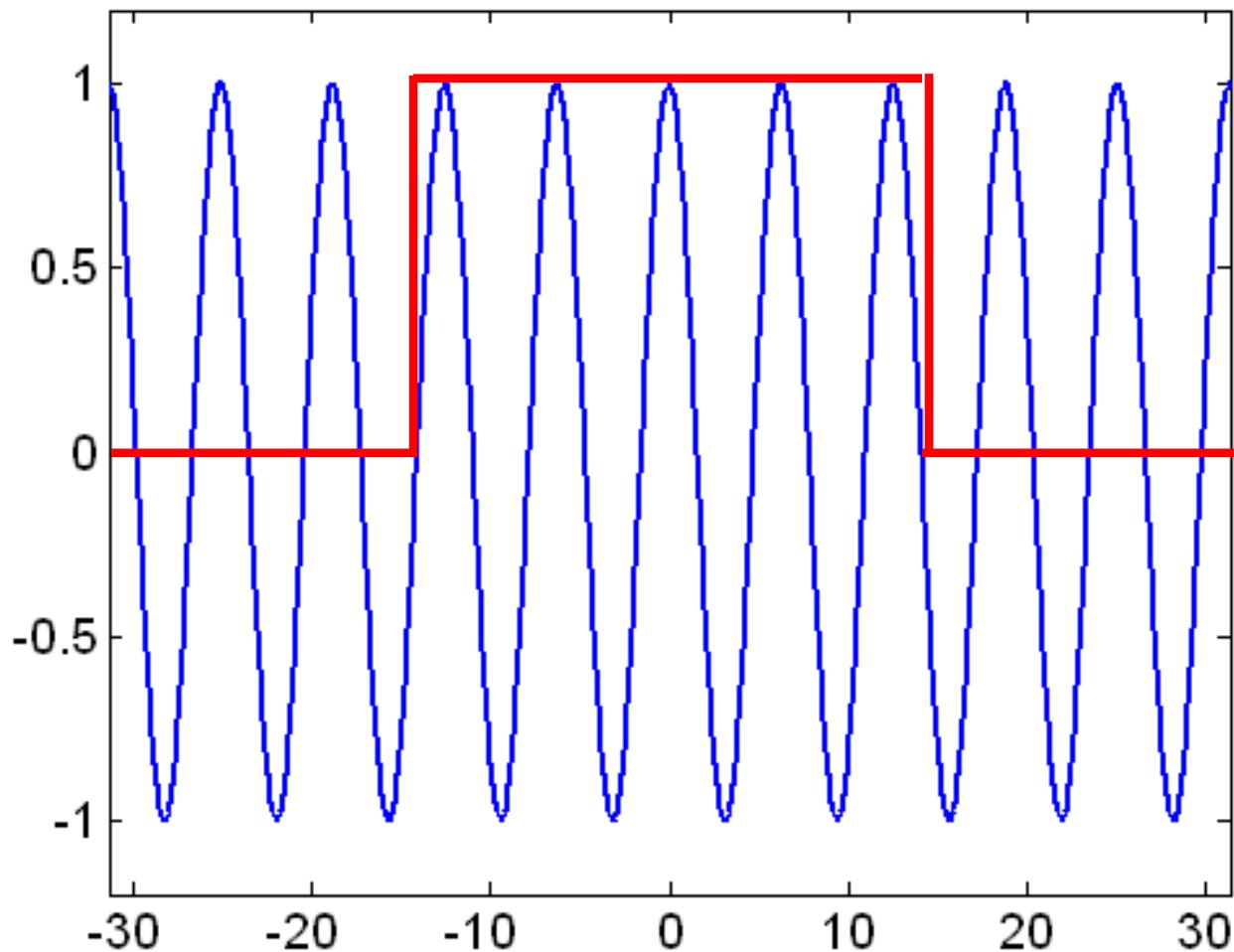
$$K_B = 1.38 \times 10^{-23} \frac{J}{K^o}$$

$$SNR \approx \frac{\|S(f)\|^2}{K_B T B}$$

# Truncated sinusoid



# Integration time



— · · · · · · · · · · —  
 $T_{int}$

# Spectrum of any radiated truncated harmonic signal

$$s_n(t) = \cos(2\pi f_n t) \Pi\left(\frac{t}{T_{\text{int}}}\right)$$

$$FT\left(\Pi\left(\frac{t}{T_{\text{int}}}\right)\right) = T_{\text{int}} \text{sinc}(\pi f T_{\text{int}})$$

$$FT\left(\cos(2\pi f_n t)\right) = \frac{1}{2} \left\{ \delta(f - f_n) + \delta(f + f_n) \right\}$$

$$S_n(f) = \frac{T_{\text{int}}}{2} \left\{ \text{sinc}(\pi T_{\text{int}} (f - f_n)) + \text{sinc}(\pi T_{\text{int}} (f + f_n)) \right\}$$

**Let us consider the “pieces”**

$$\text{sinc}\left(\pi T_{\text{int}}(f - f_n)\right), \text{sinc}\left(\pi T_{\text{int}}(f + f_n)\right)$$

**The main lobe is wide  $1/T_{\text{int}}$  for both pieces**

$$SNR \approx \frac{\|S_n(f)\|^2}{K_B TB_n} \approx \frac{T_{\text{int}} \|S_n(f)\|^2}{K_B T}$$

**Prolonging the integration time the SNR increases, but the measurement requires more time**

- *The integration time is a default parameter chosen by the manufacturer.*
- *Possibly, there is the possibility to extend the default integration time times a factor.*
- *The integration time is usually the same for all the harmonics spanned by the stepped frequency system.*

# NON-AMBIGUOUS TIME INTERVAL

The time windows where we can reliably examine the synthetic pulses is given by

$$T_{\max} = \frac{1}{\Delta f}$$

The depth investigated cannot exceed the non-ambiguous level

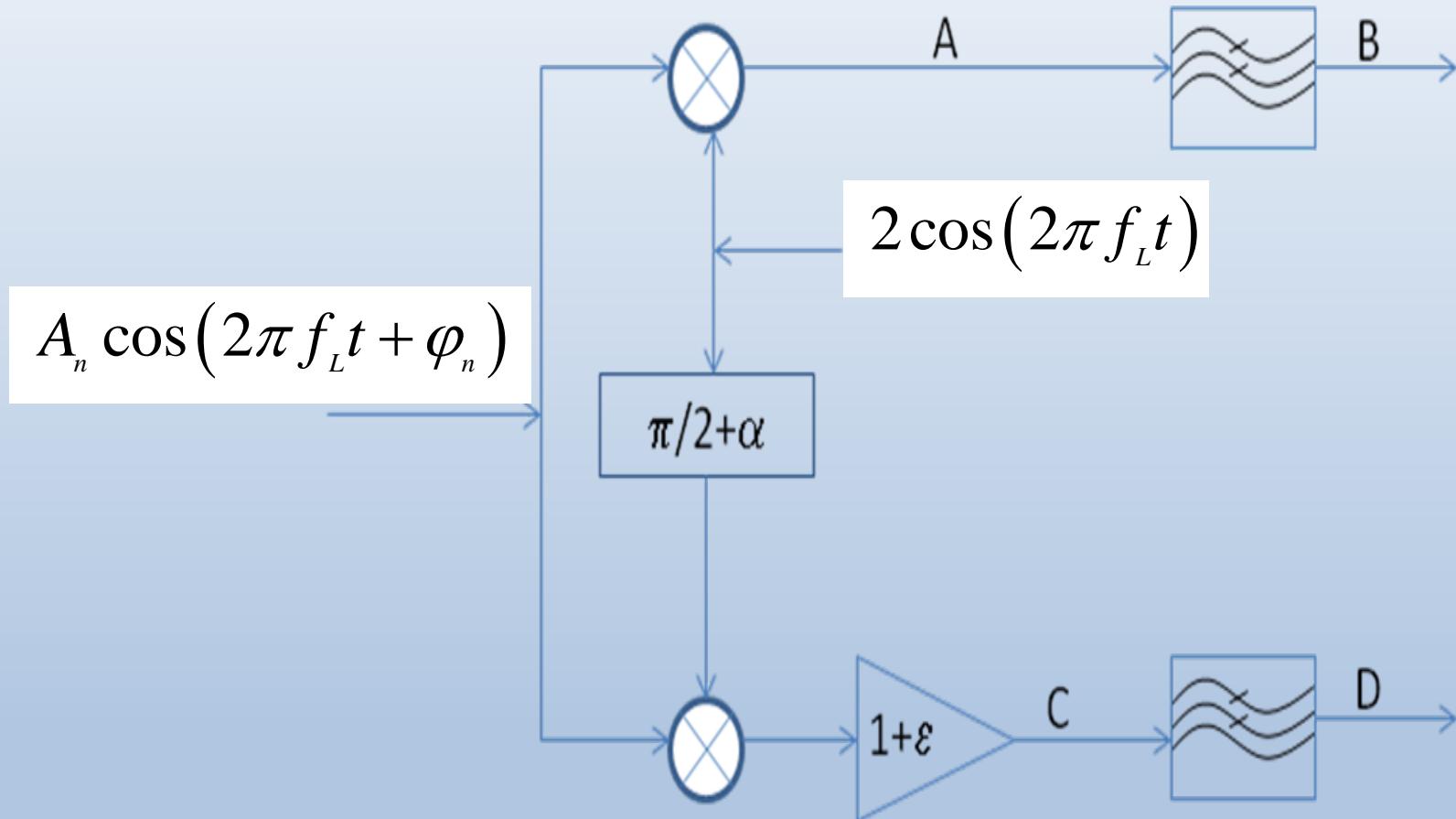
$$D_{\max} = \frac{c T_{\max}}{2} = \frac{c}{2 \Delta f}$$

**The frequency step cannot exceed the maximum value:**

$$\Delta f \leq \frac{c}{2D_{\max}} = \frac{c_o}{2\sqrt{\epsilon_r \mu_r} D_{\max}}$$

**N.B.:  $D_{\max}$  depends on the penetration of the signal, not on the maximum depth of interest.**

# Effect of possible imperfections on the demodulation chain



**Received synthetic pulse for a target at depth level  $t_o$  (the spectrum of the signal is considered flat in its band, sampled with  $2N+1$  frequencies)**

$$s_r(t) \approx K \times$$

$$\times \left\{ \sqrt{\left(1 + \frac{\varepsilon}{2}\right)^2 + \frac{\alpha^2}{4}} \cos\left(2\pi f_c(t - t_o) + \theta - \operatorname{tg}^{-1} \frac{\alpha}{2 + \varepsilon}\right) \frac{\sin((2N+1)\pi\Delta f(t - t_o))}{\sin(\pi\Delta f(t - t_o))} + \right.$$

$$\left. - \sqrt{\frac{\varepsilon^2}{4} + \frac{\alpha^2}{4}} \cos\left(2\pi f_c(t + t_o) - \theta - \operatorname{tg}^{-1} \frac{\alpha}{\varepsilon}\right) \frac{\sin((2N+1)\pi\Delta f(t + t_o))}{\sin(\pi\Delta f(t + t_o))} \right\}$$

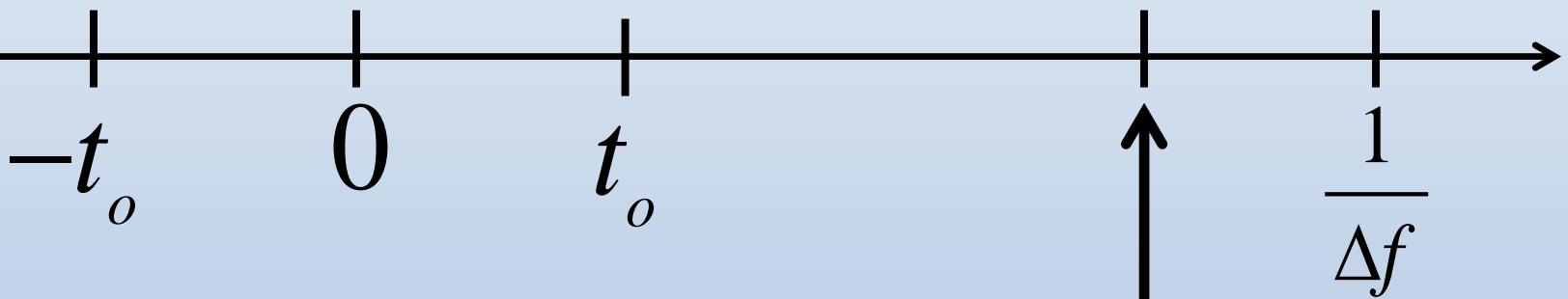
***Hermitian image at  $\frac{1}{\Delta f} - t_o$***

# Signal to Hermitian image ratio SHR

$$s_r(t) \approx K \times$$
$$\times \left\{ \sqrt{\left(1 + \frac{\varepsilon}{2}\right)^2 + \frac{\alpha^2}{4}} \cos\left(2\pi f_c(t - t_o) + \theta - \operatorname{tg}^{-1} \frac{\alpha}{2 + \varepsilon}\right) \frac{\sin((2N+1)\pi\Delta f(t - \bar{t}))}{\sin(\pi\Delta f(t - \bar{t}))} + \right.$$
$$\left. - \sqrt{\frac{\varepsilon^2}{4} + \frac{\alpha^2}{4}} \cos\left(2\pi f_c(t + t_o) - \theta - \operatorname{tg}^{-1} \frac{\alpha}{\varepsilon}\right) \frac{\sin((2N+1)\pi\Delta f(t + \bar{t}))}{\sin(\pi\Delta f(t + \bar{t}))} \right\}$$

$$SHR \approx \frac{\sqrt{\left(1 + \frac{\varepsilon}{2}\right)^2 + \frac{\alpha^2}{4}}}{\sqrt{\frac{\varepsilon^2}{4} + \frac{\alpha^2}{4}}} \approx \frac{2}{\sqrt{\varepsilon^2 + \alpha^2}}$$

# Counteraction against Hermitian images: halving the frequency step at parity of maximum investigated time depth



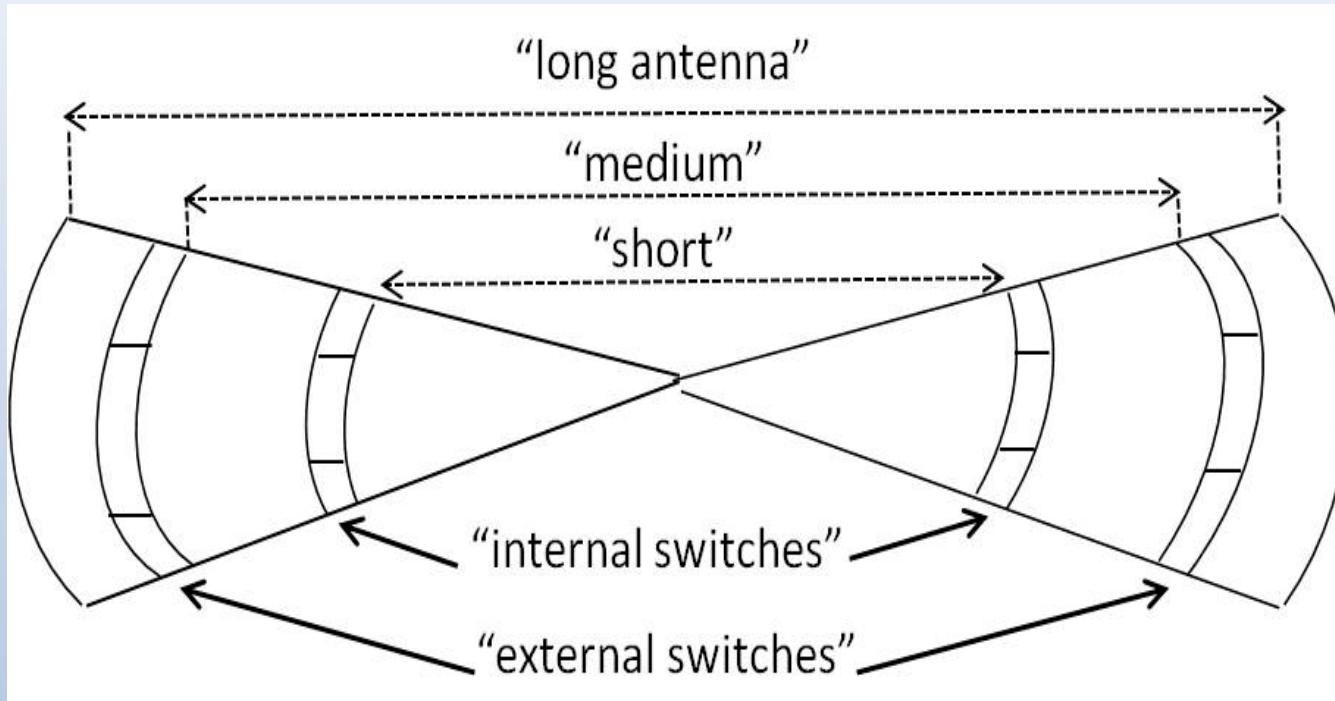
$$\Delta f \leq \frac{c}{4D_{\max}} = \frac{c_o}{4\sqrt{\varepsilon_r \mu_r} D_{\max}}$$

$$T_{\max} = \frac{1}{2\Delta f}$$

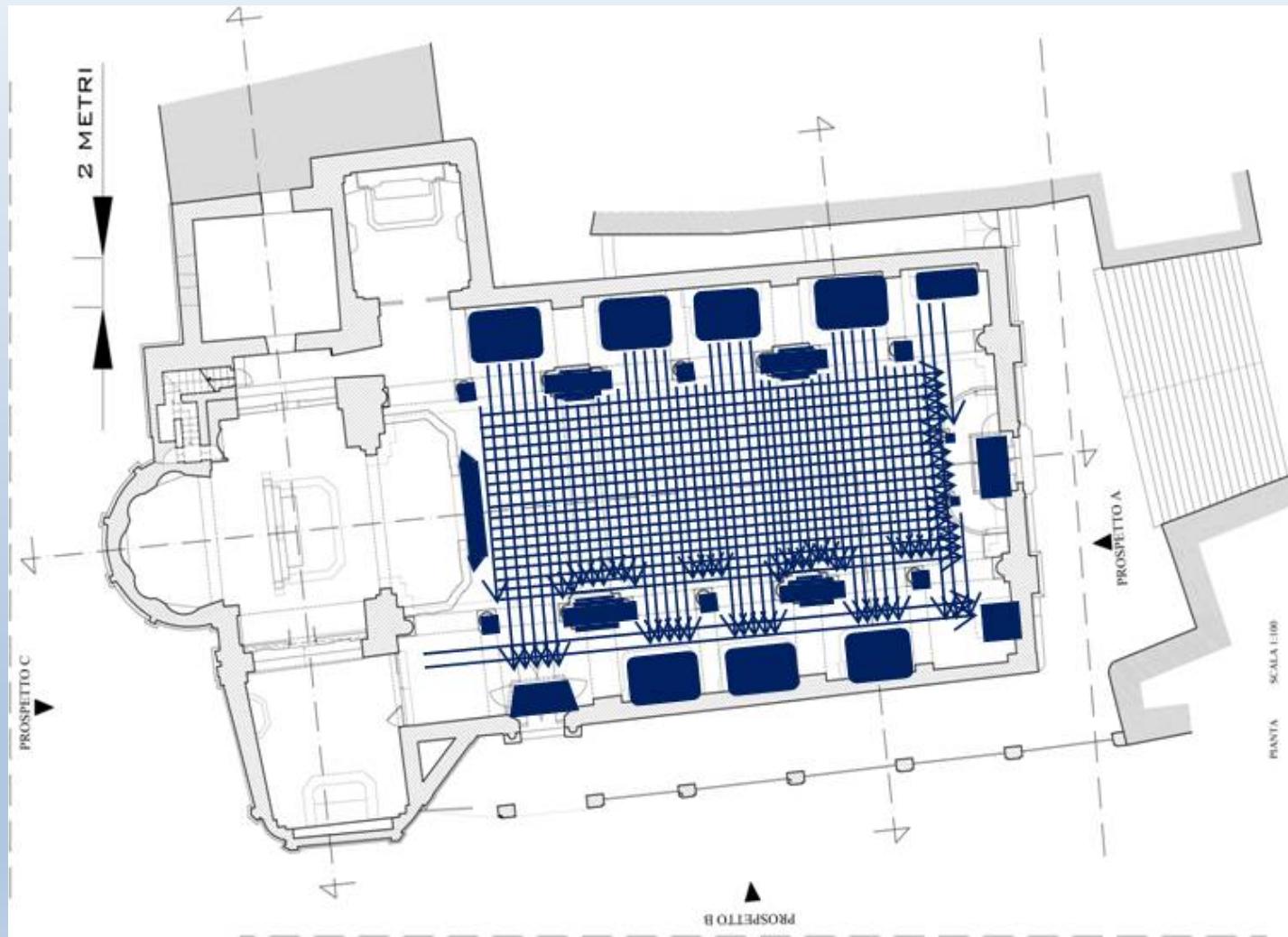
# The reconfigurable GPR system (50 MHz-1 GHz)

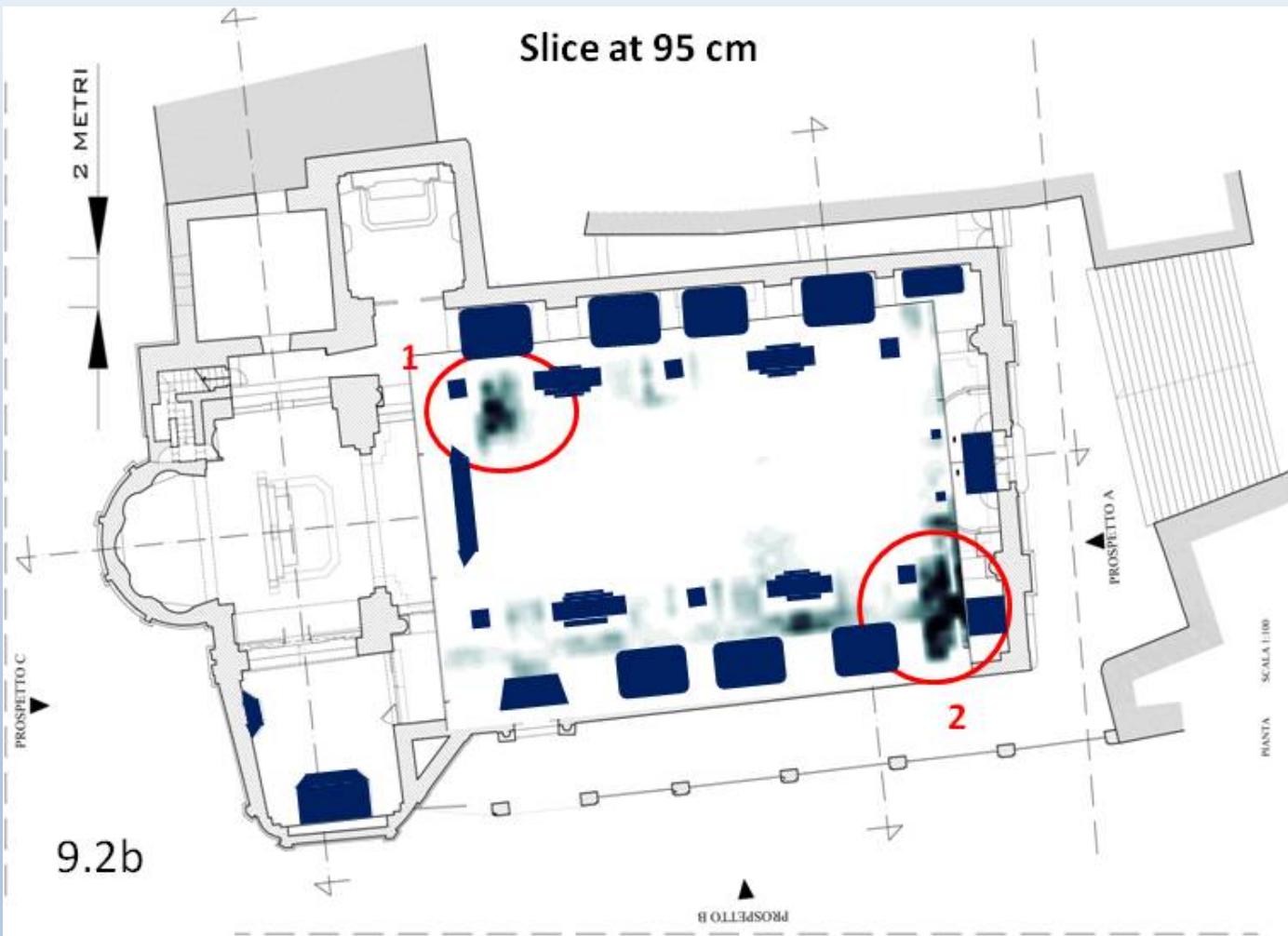


# Reconfigurable antennas

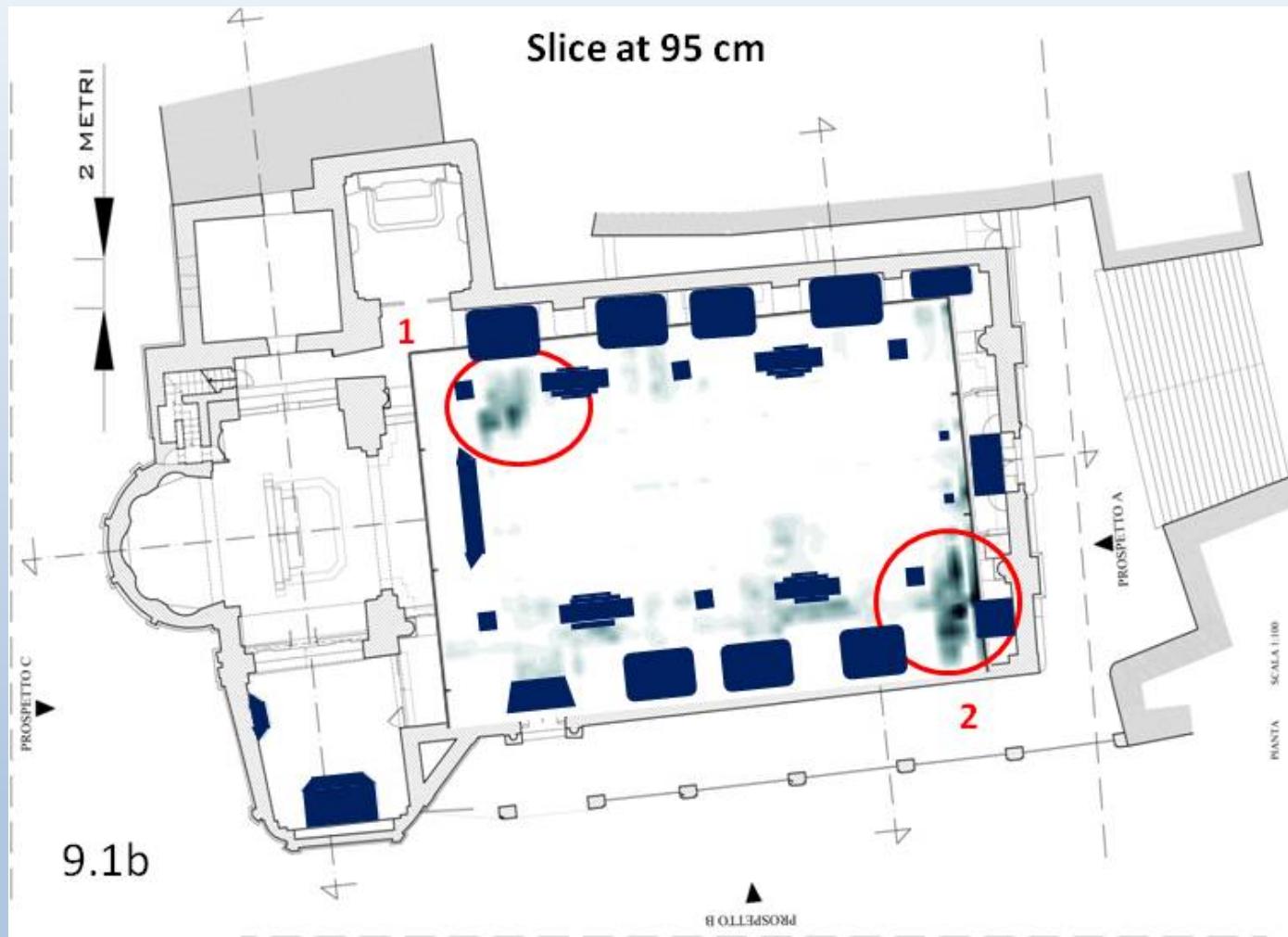


# The matrix church of Parabita





# SLICE ACHIEVED WITH A RIS-HI MODE PULSED SYSTEM

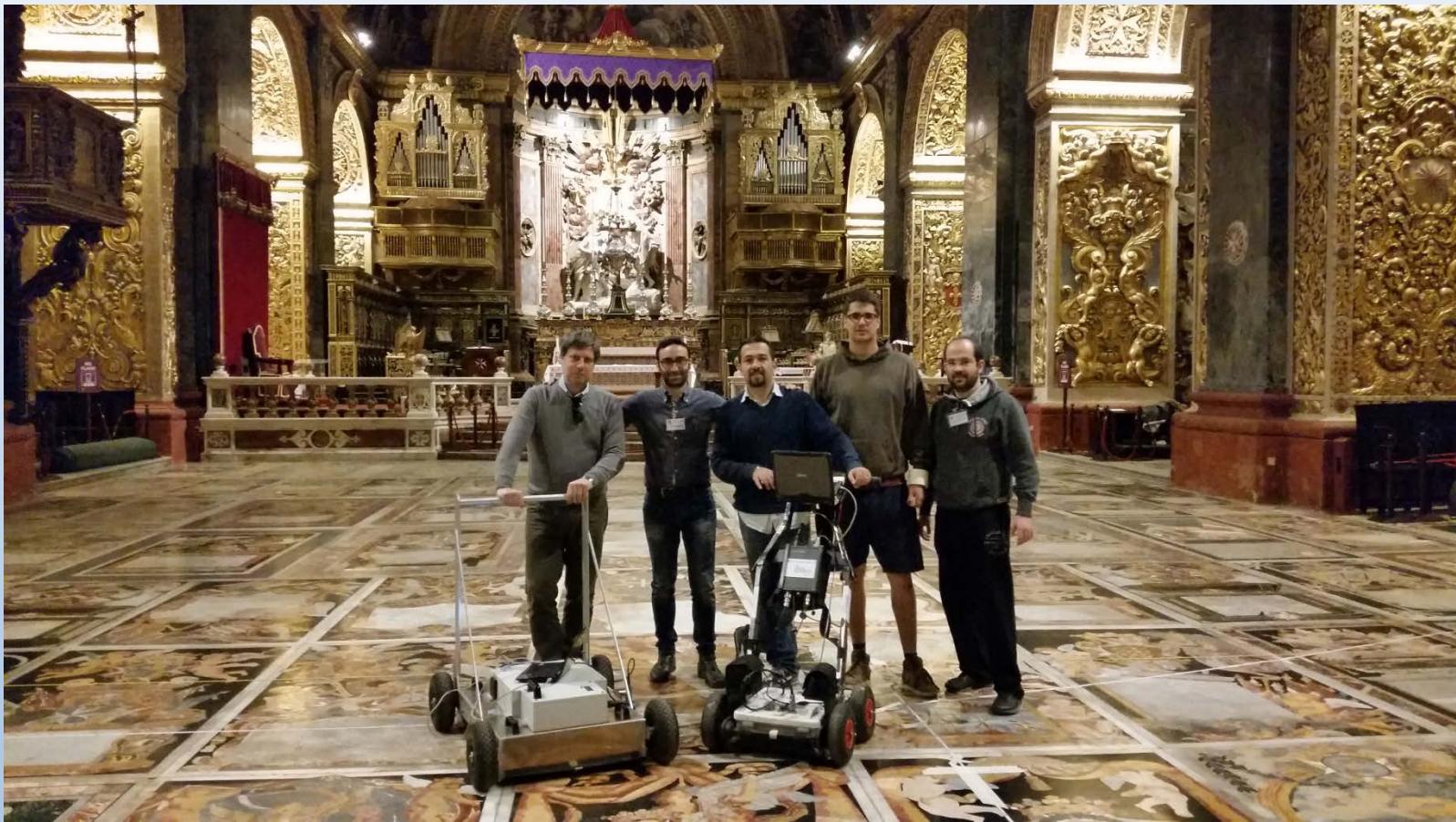




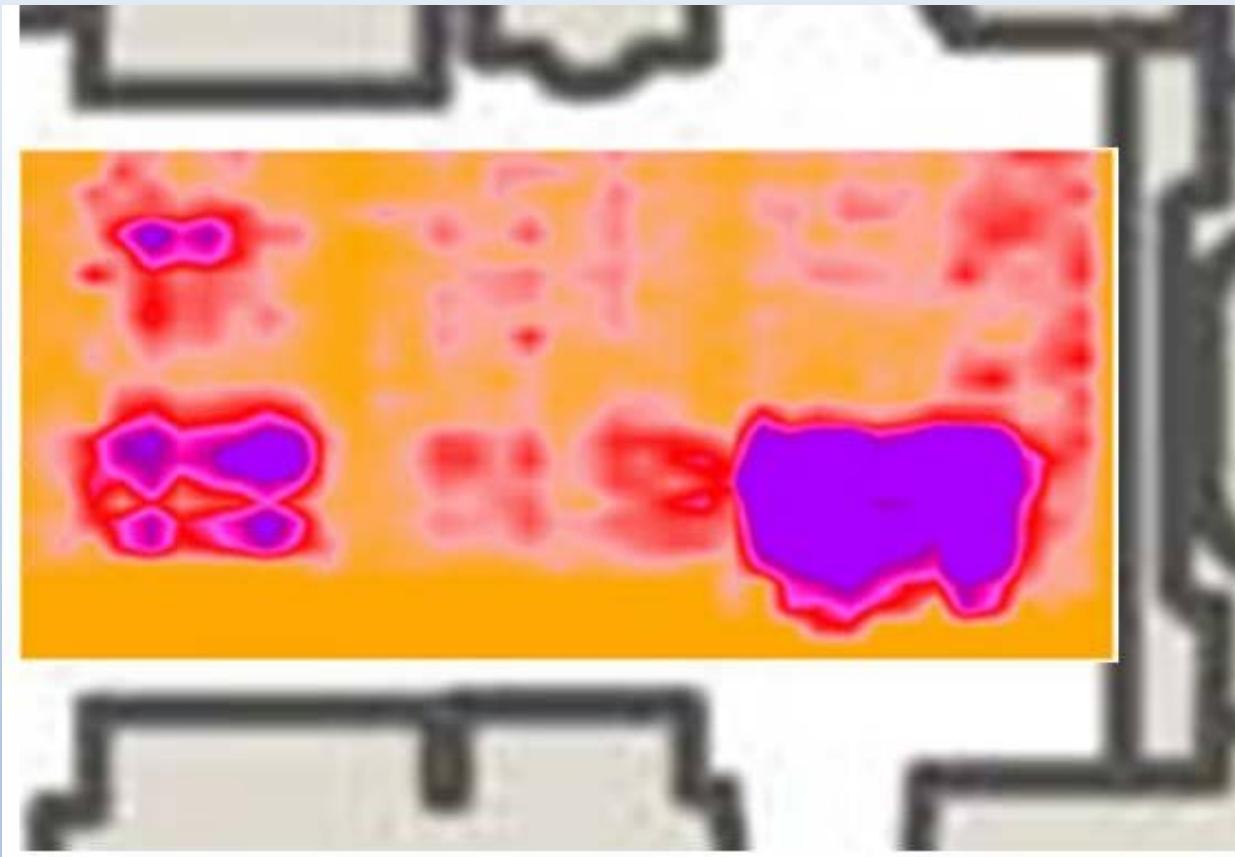


2013/04/23 14:14:06

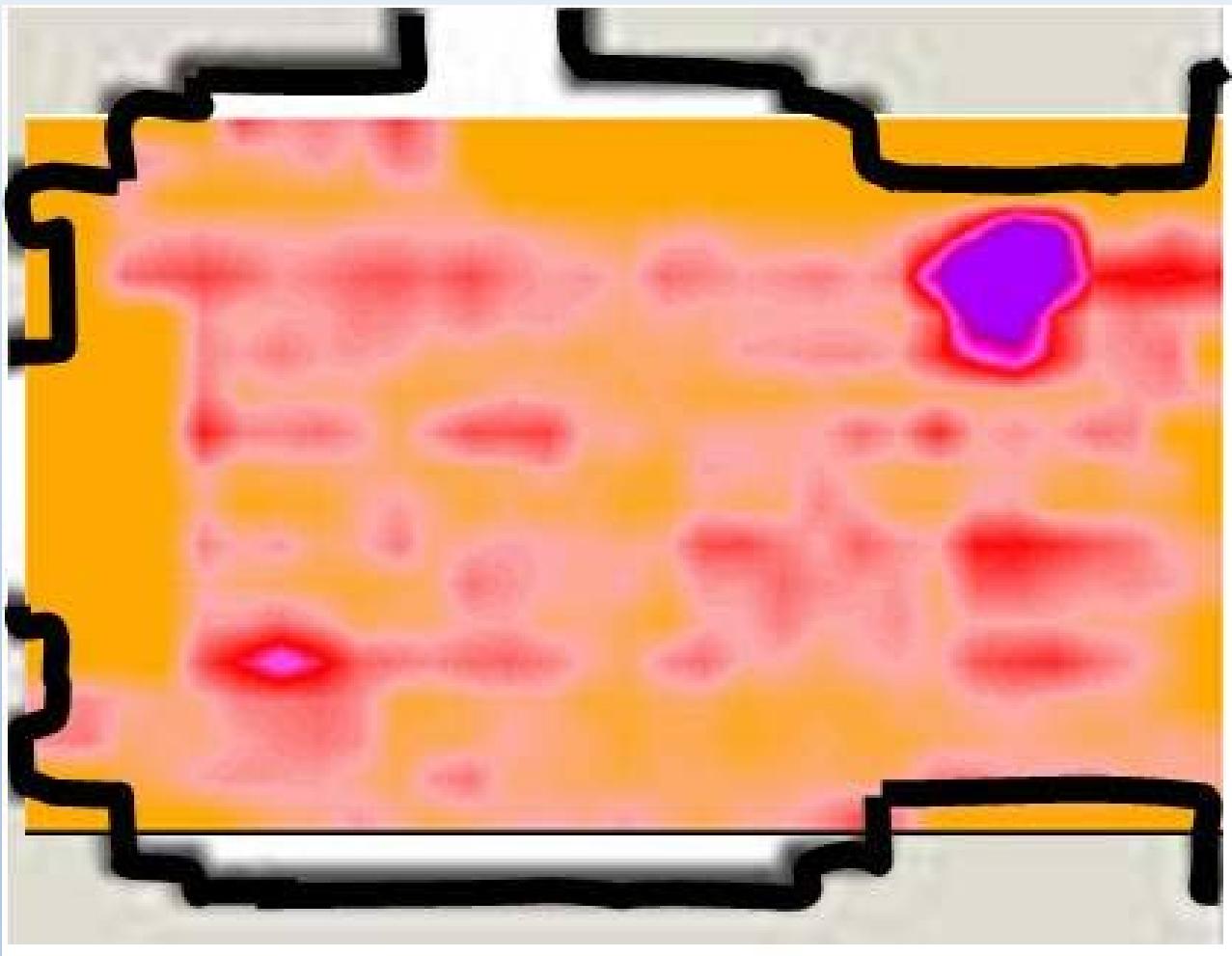
# The co-cathedral of St. John in Malta



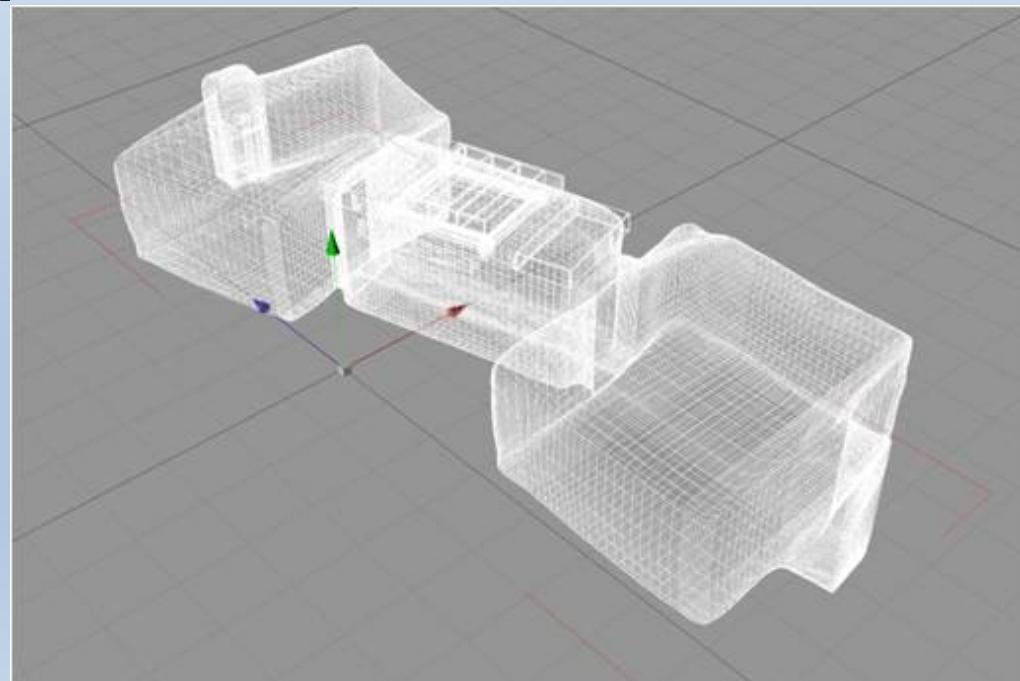
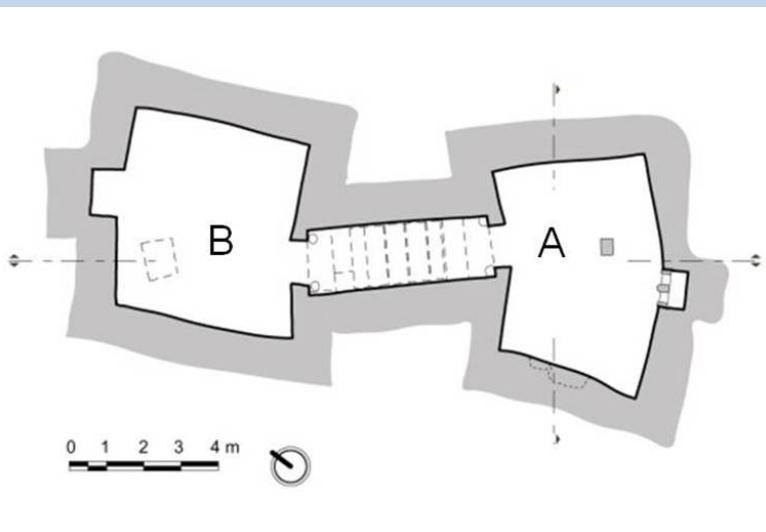
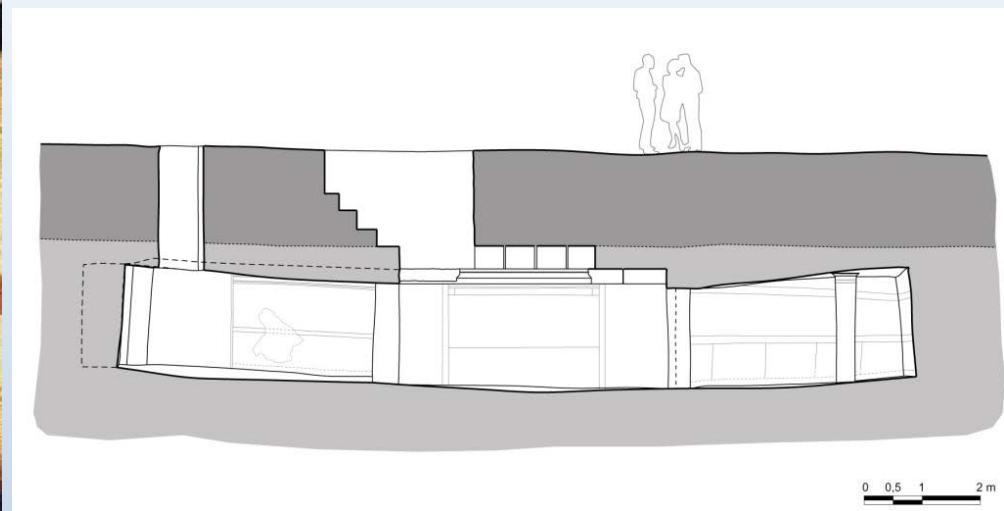
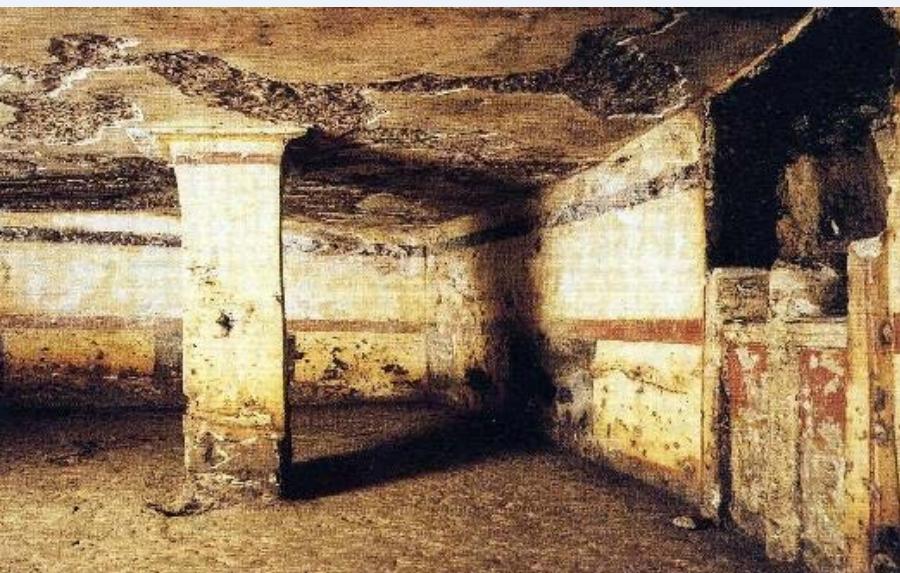
# *Chapel of Aragon*

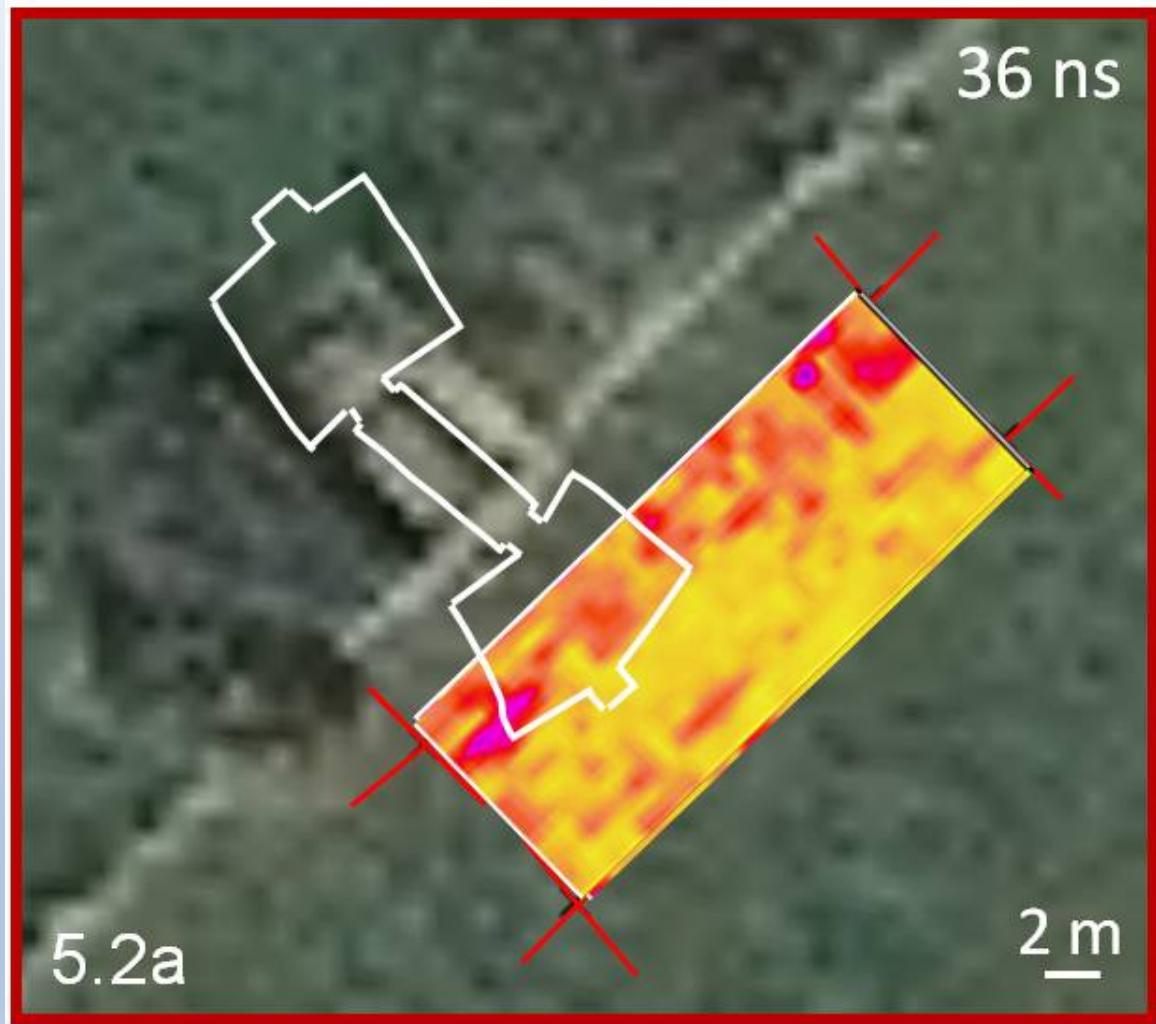


# *Chapel of the Sacristy*

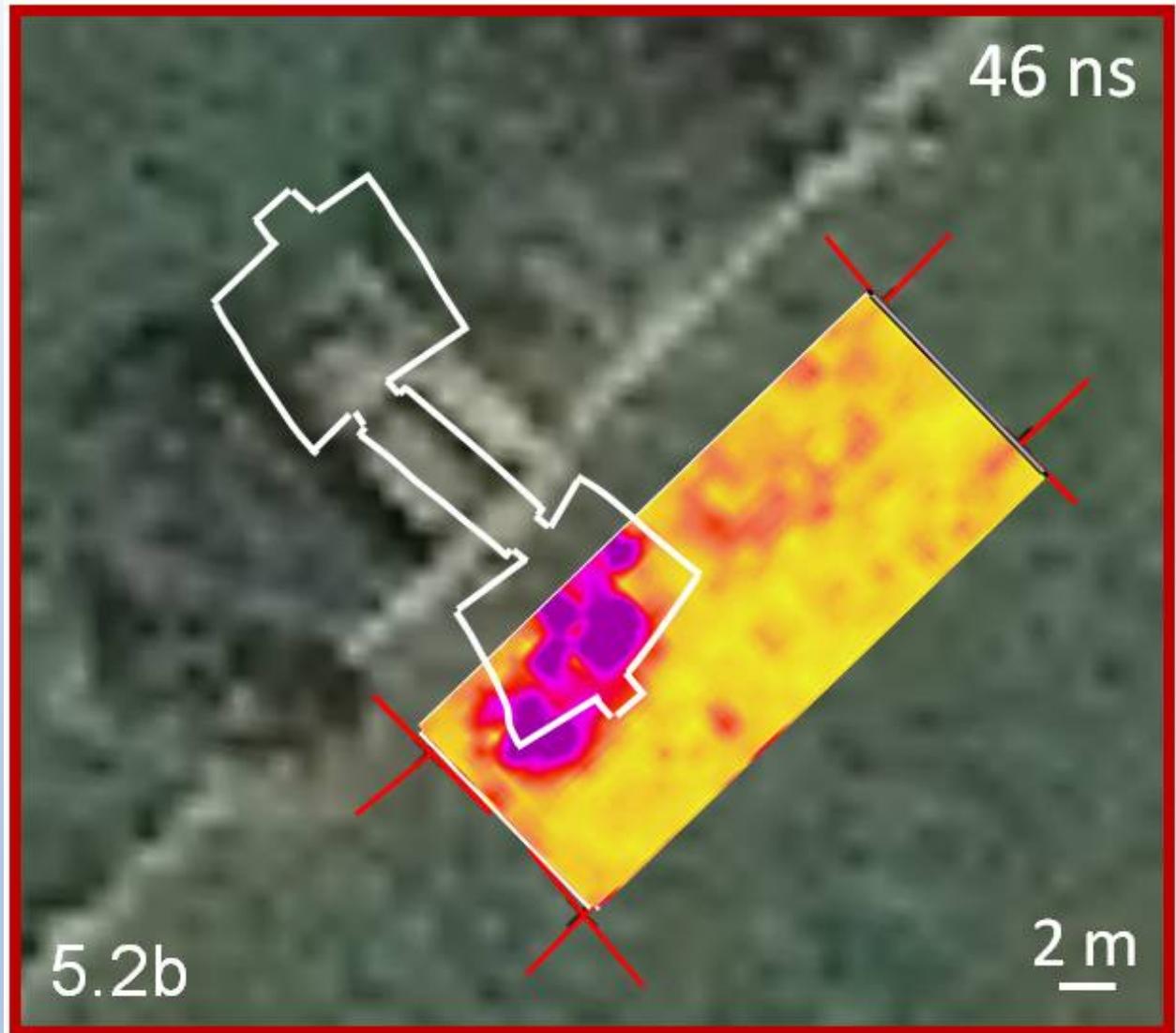


# The Tomb of the Pillar

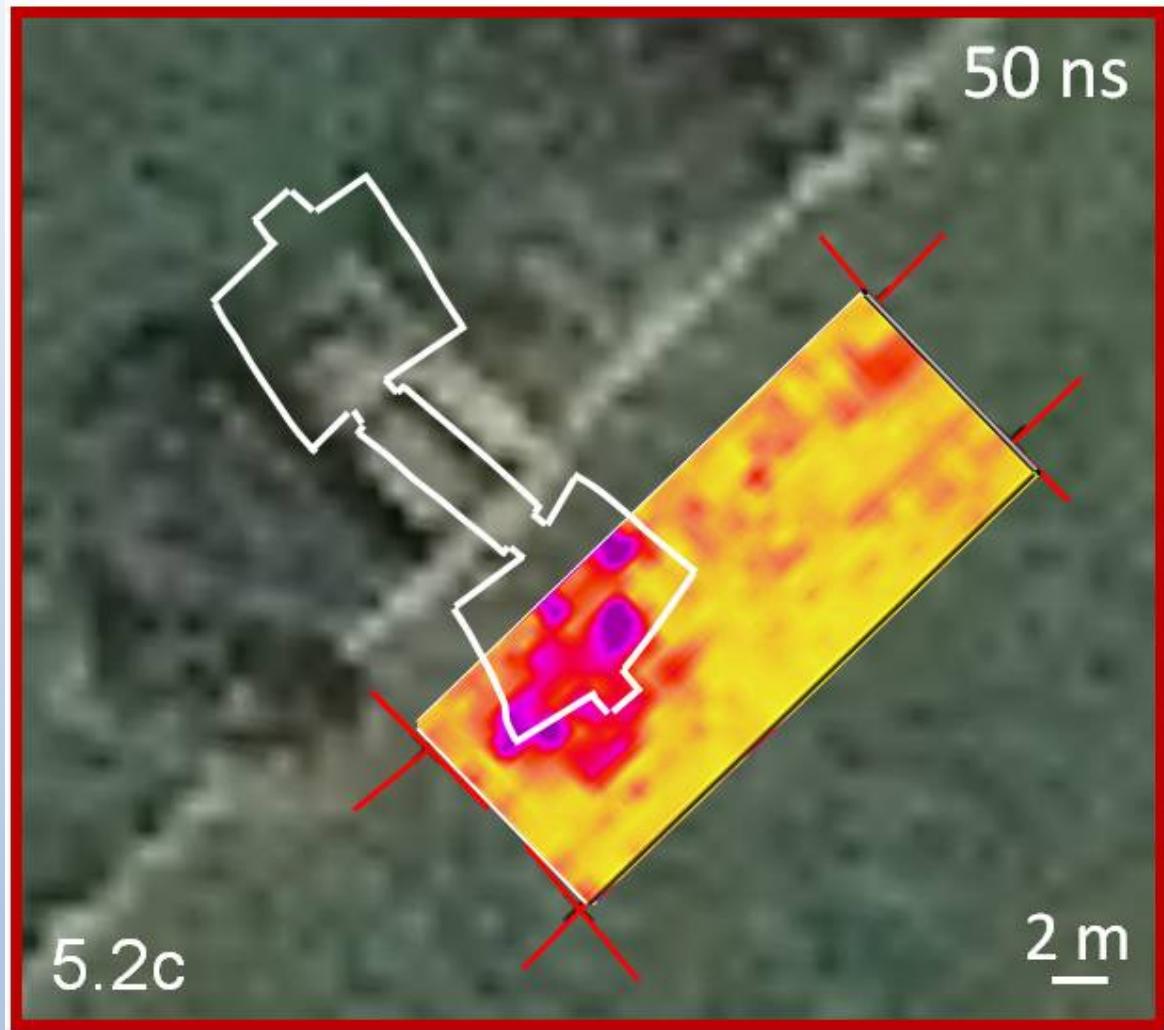




**Depth 1.26 m**



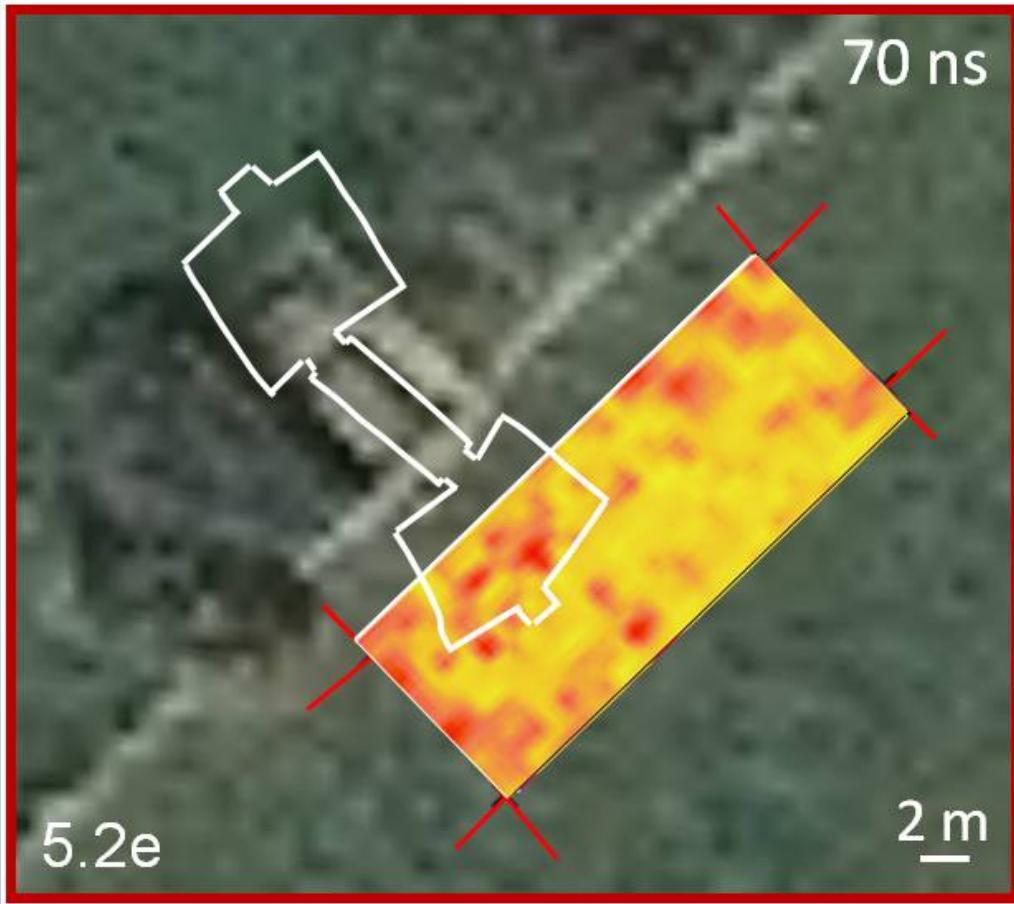
**Depth 1.61m**



**Depth 1.75m**



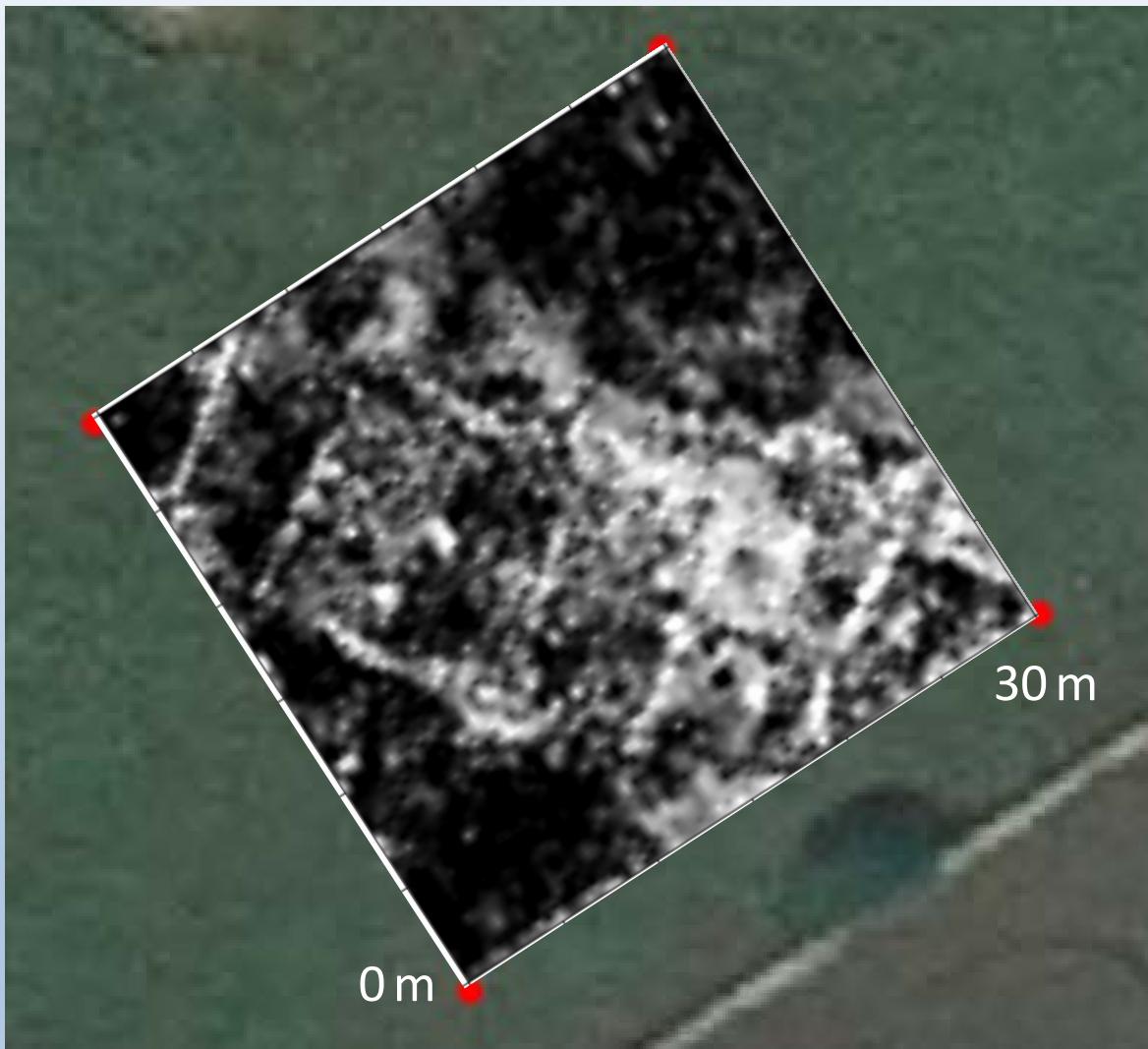
**Depth 2.20m**



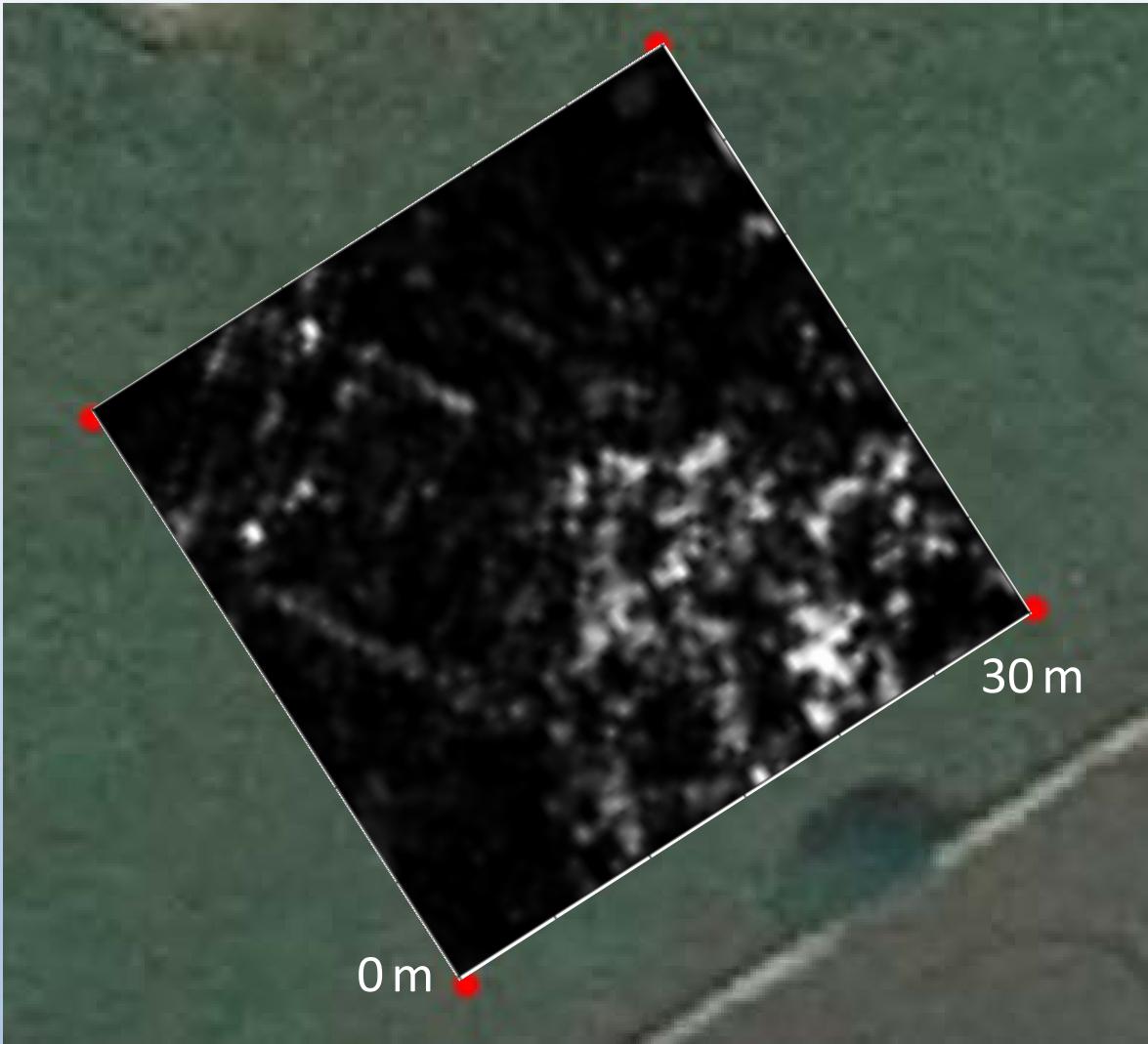
**Depth 2.45m**

**Apparent thickness of the tomb 49 cm, real thickness 2.1 m**

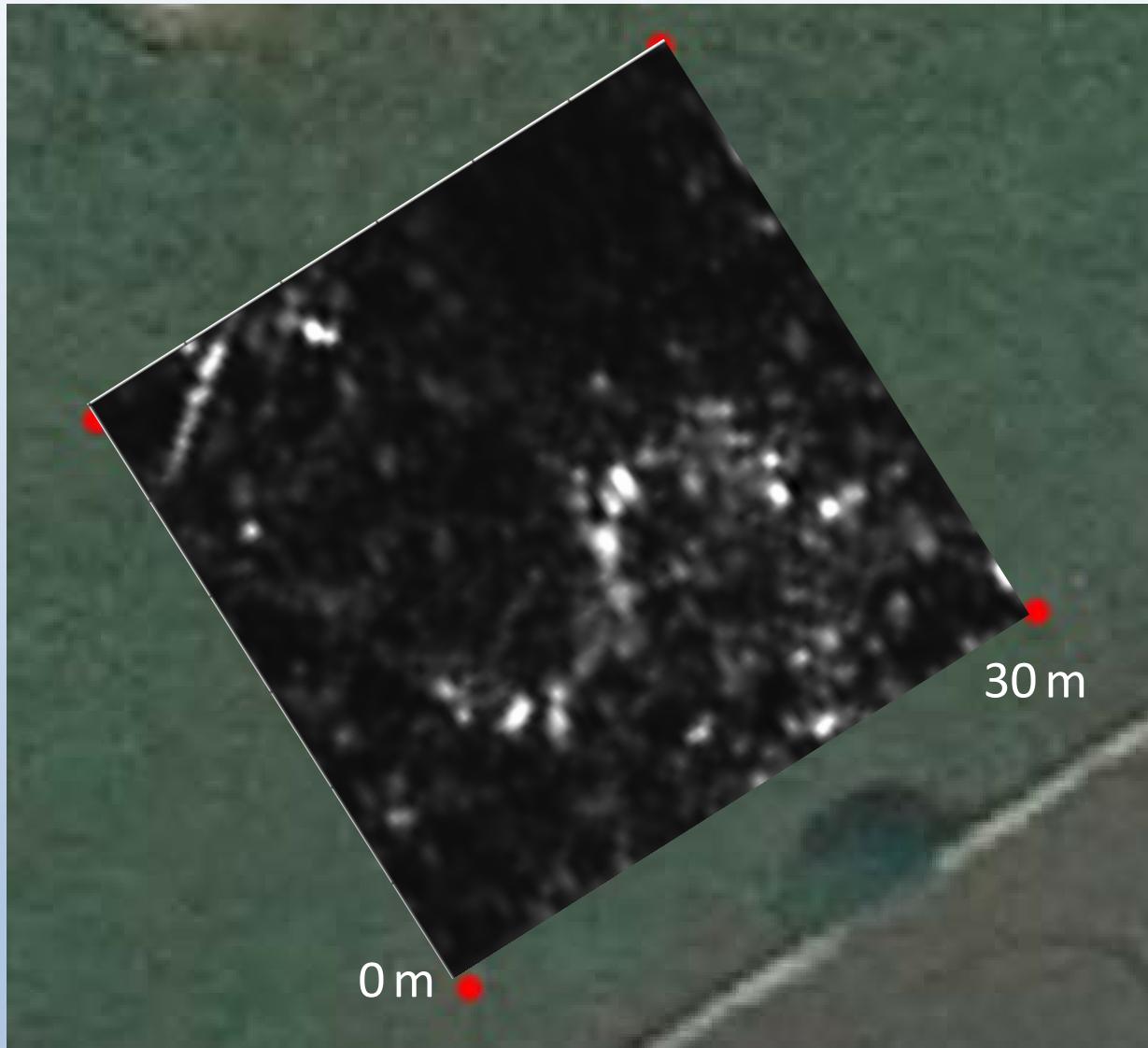
# The area of the “cryptoporticus” in Egnazia



**Depth 40 cm**

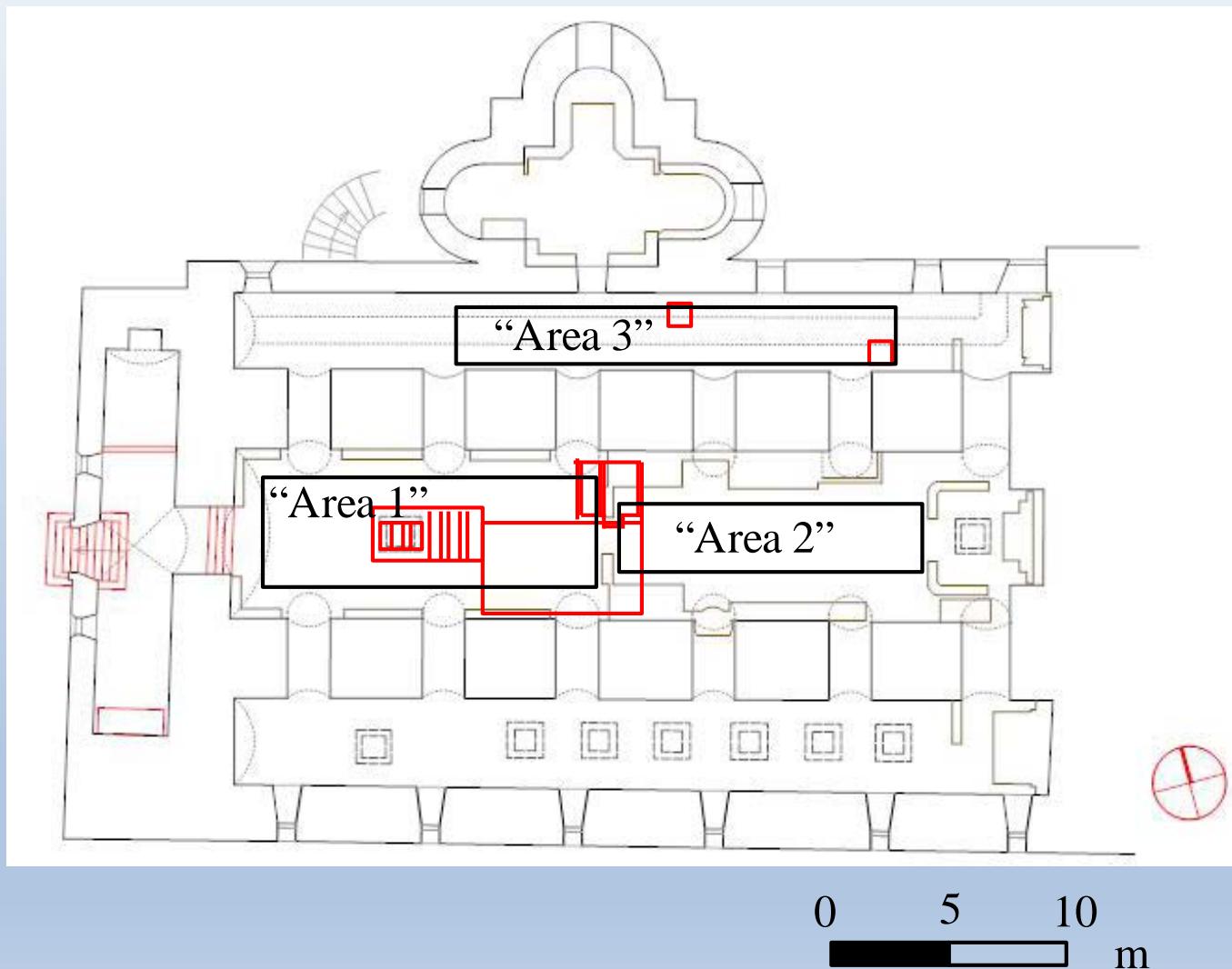


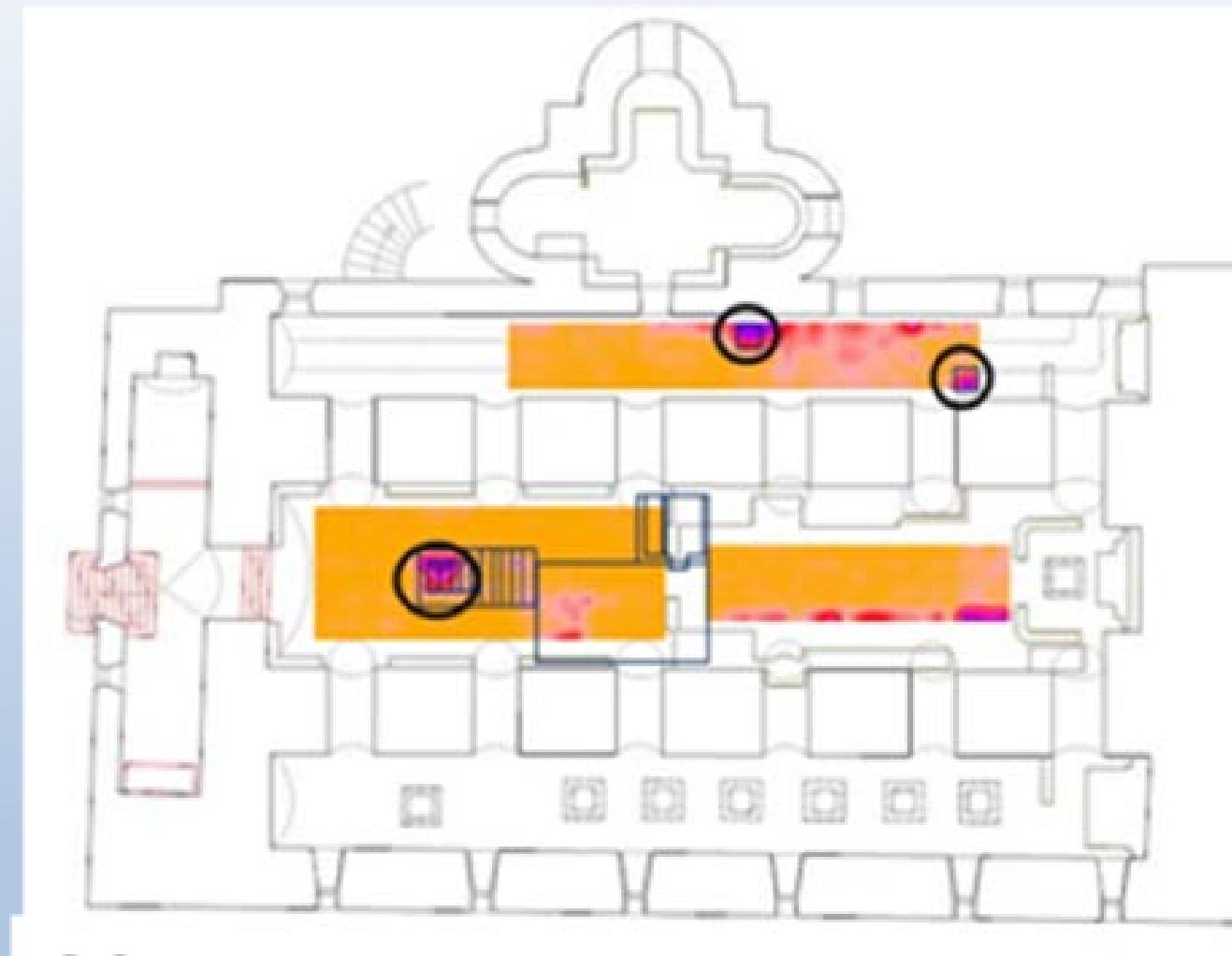
**Depth 94 cm**



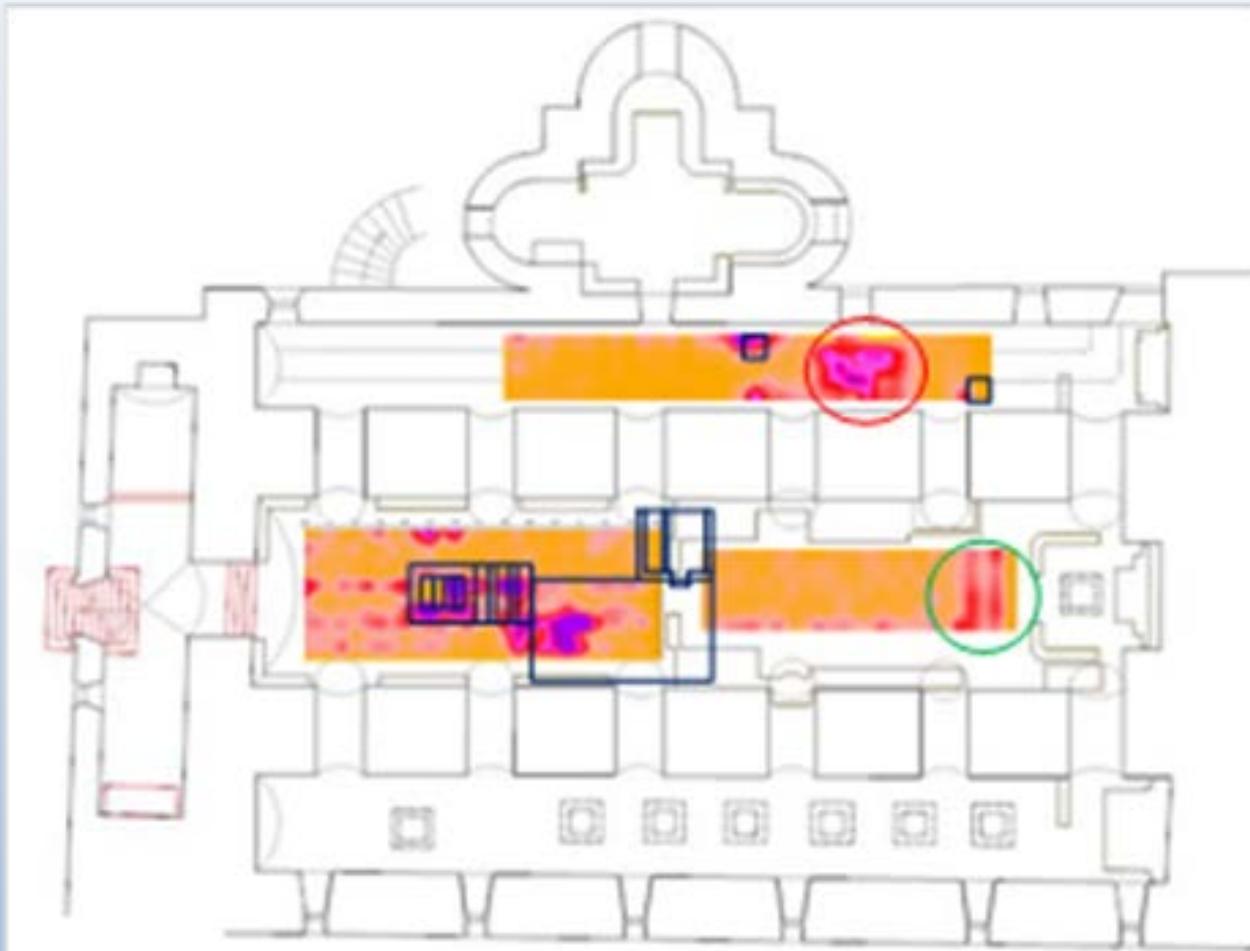
**Depth 150 cm**

# The church of Santa Croce in Gravina in Puglia

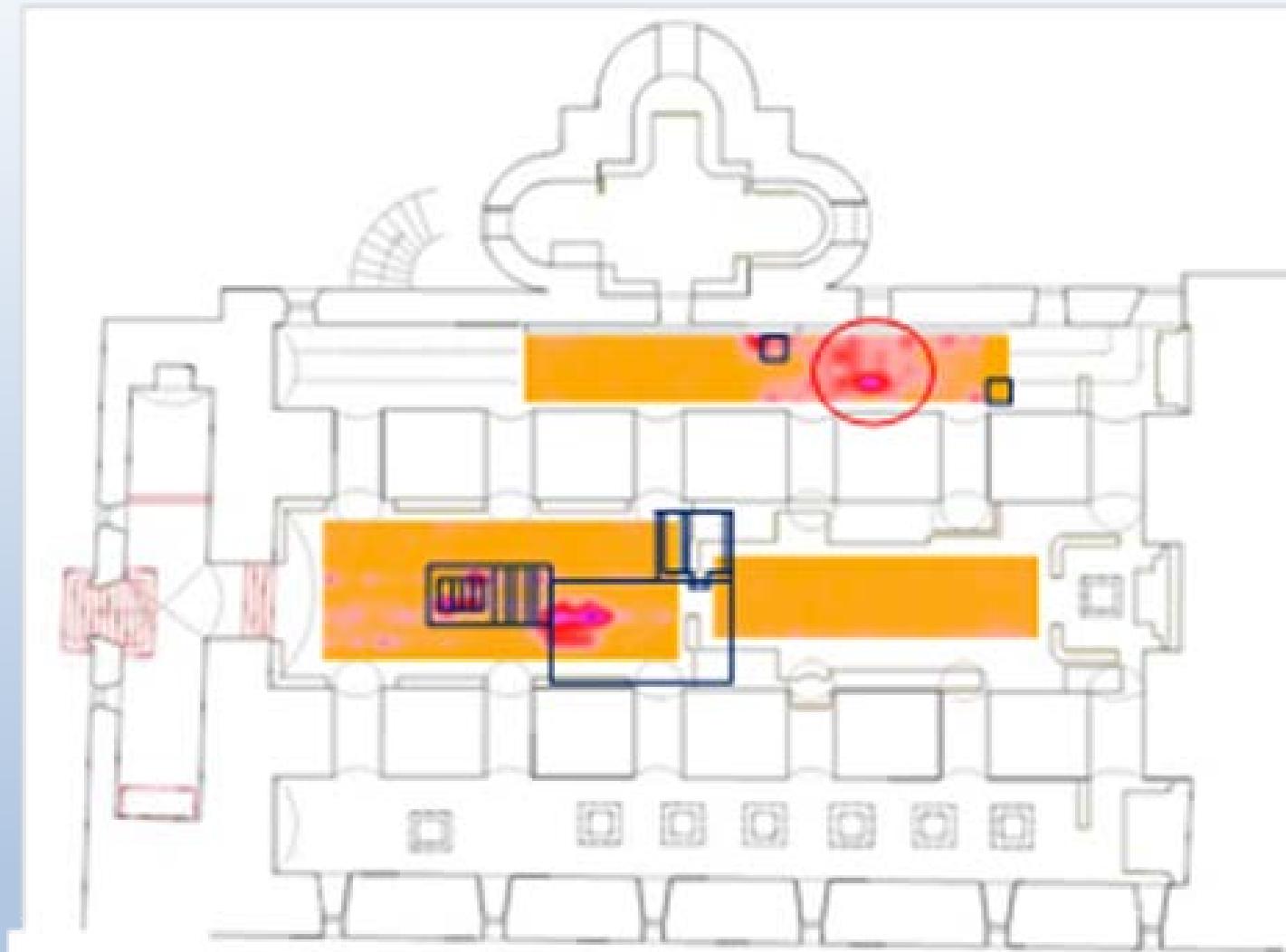




**Depth 22 cm**

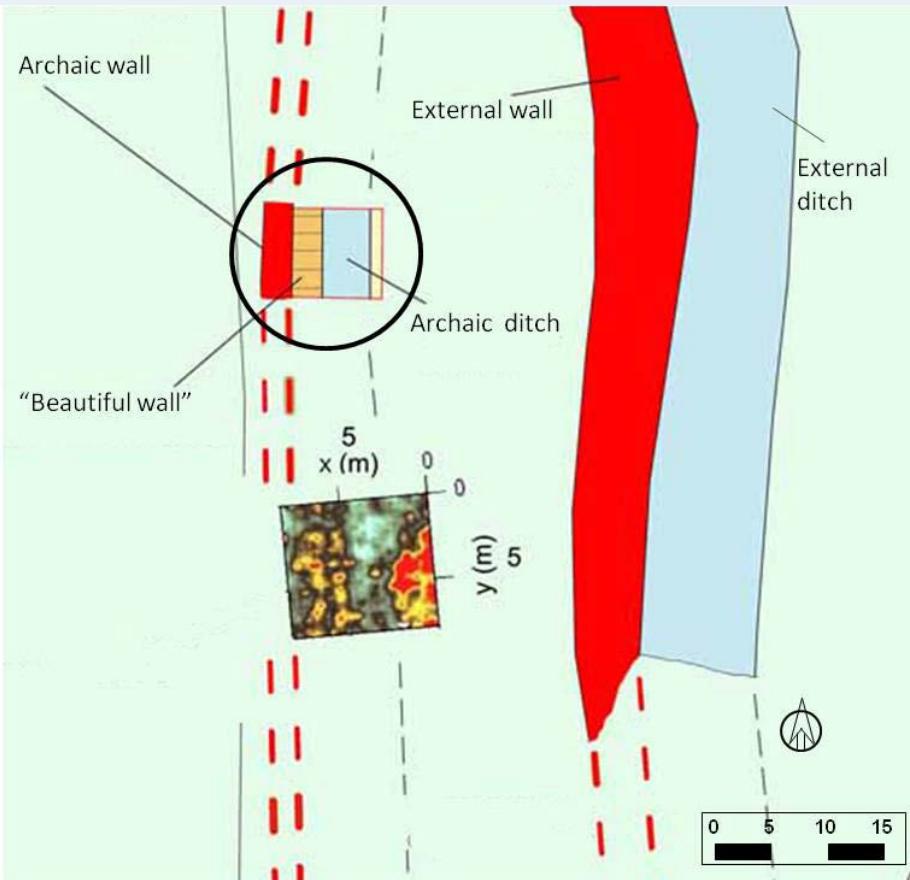


**Depth 77 cm**



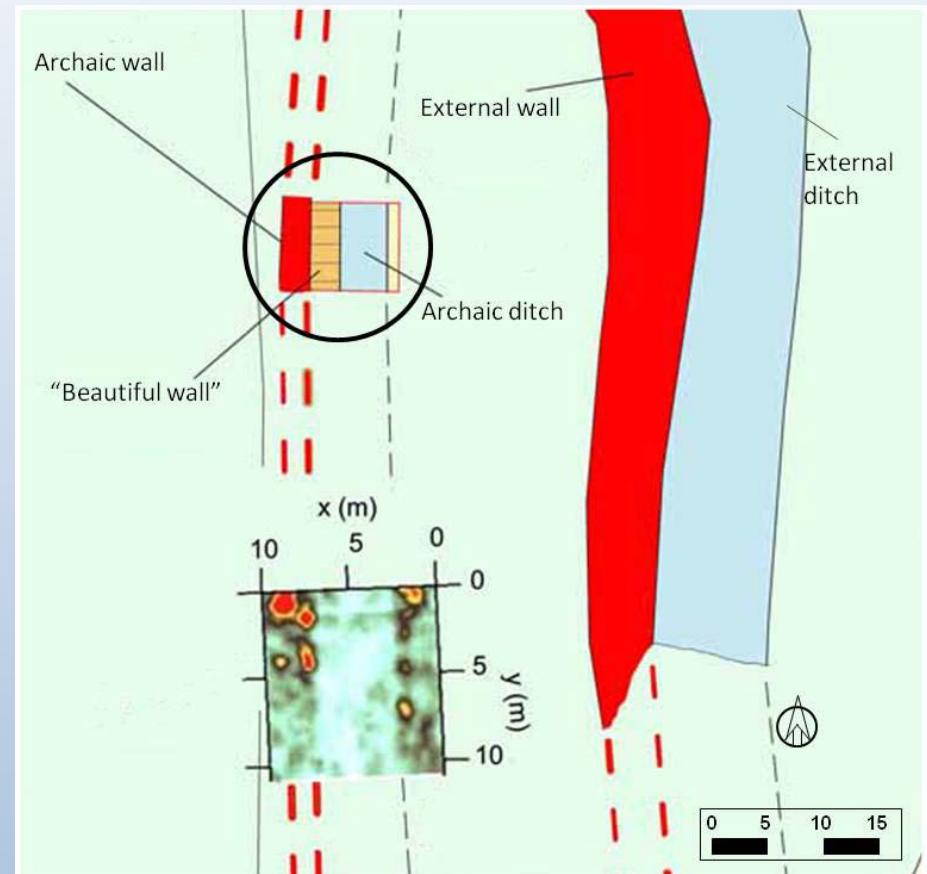
**Depth 158 cm**

# The Archaic Ditch of Manduria



Pulsed GPR

Depth 360 cm



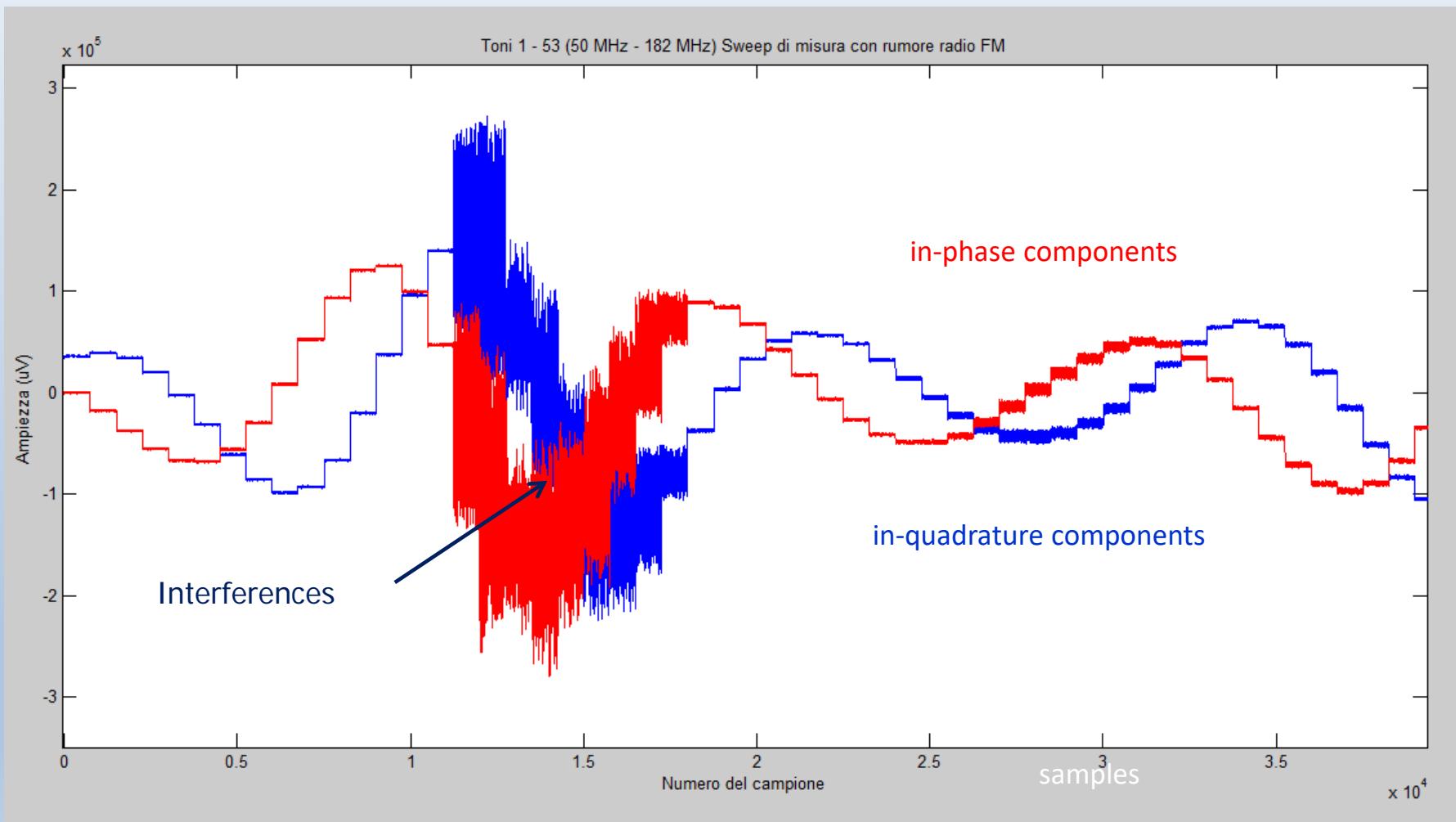
Prototype

# Reconfigurable integration times

$$f_n \leftrightarrow T_{\text{int } n}$$

**Reconfigurable radiated power at each frequency**

# The reconfiguration of the integration times as strategy again interferences



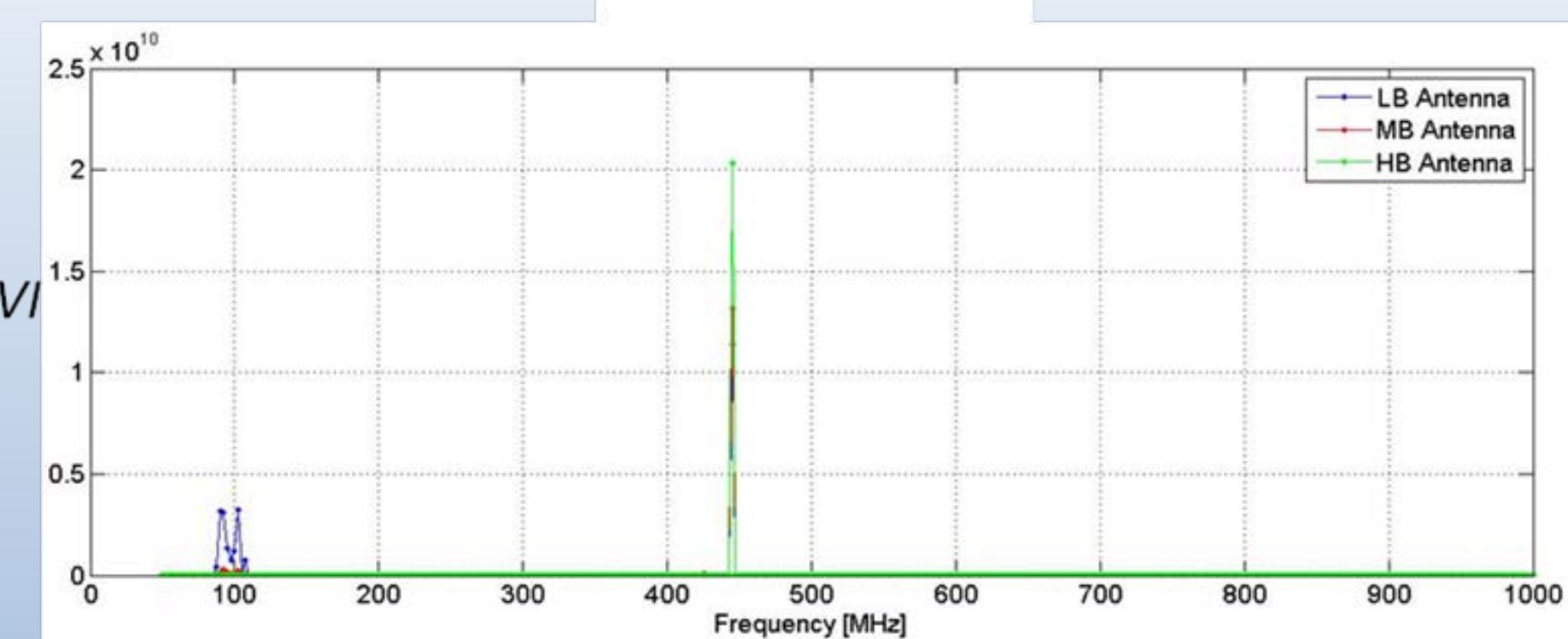
# Variance of the samples

$$\left\{ \begin{array}{l} \sigma_I^2 = \frac{I_1^2 + I_2^2 + \dots + I_N^2}{N} - \left( \frac{I_1 + I_2 + \dots + I_N}{N} \right)^2 \\ \sigma_Q^2 = \frac{Q_1^2 + Q_2^2 + \dots + Q_N^2}{N} - \left( \frac{Q_1 + Q_2 + \dots + Q_N}{N} \right)^2 \end{array} \right.$$

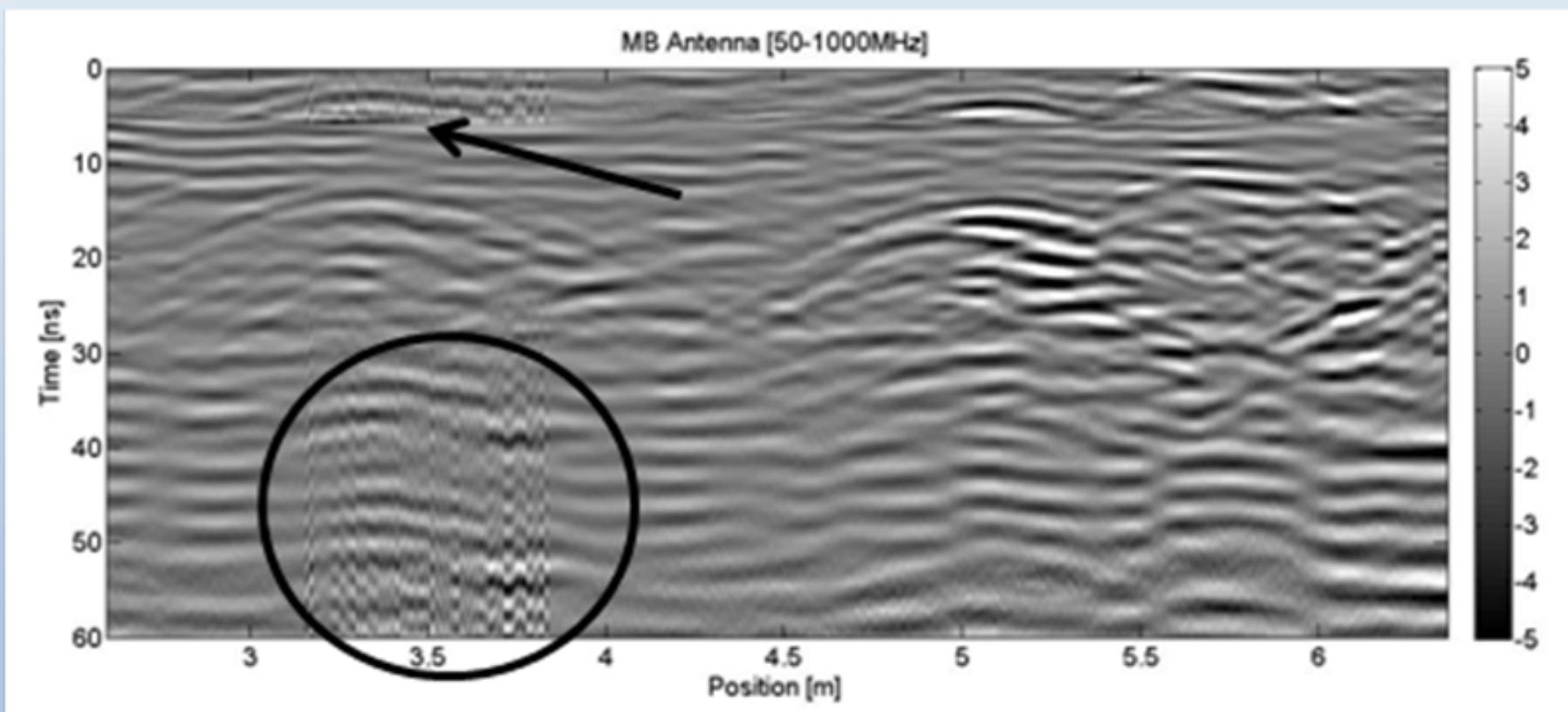
# An experiment



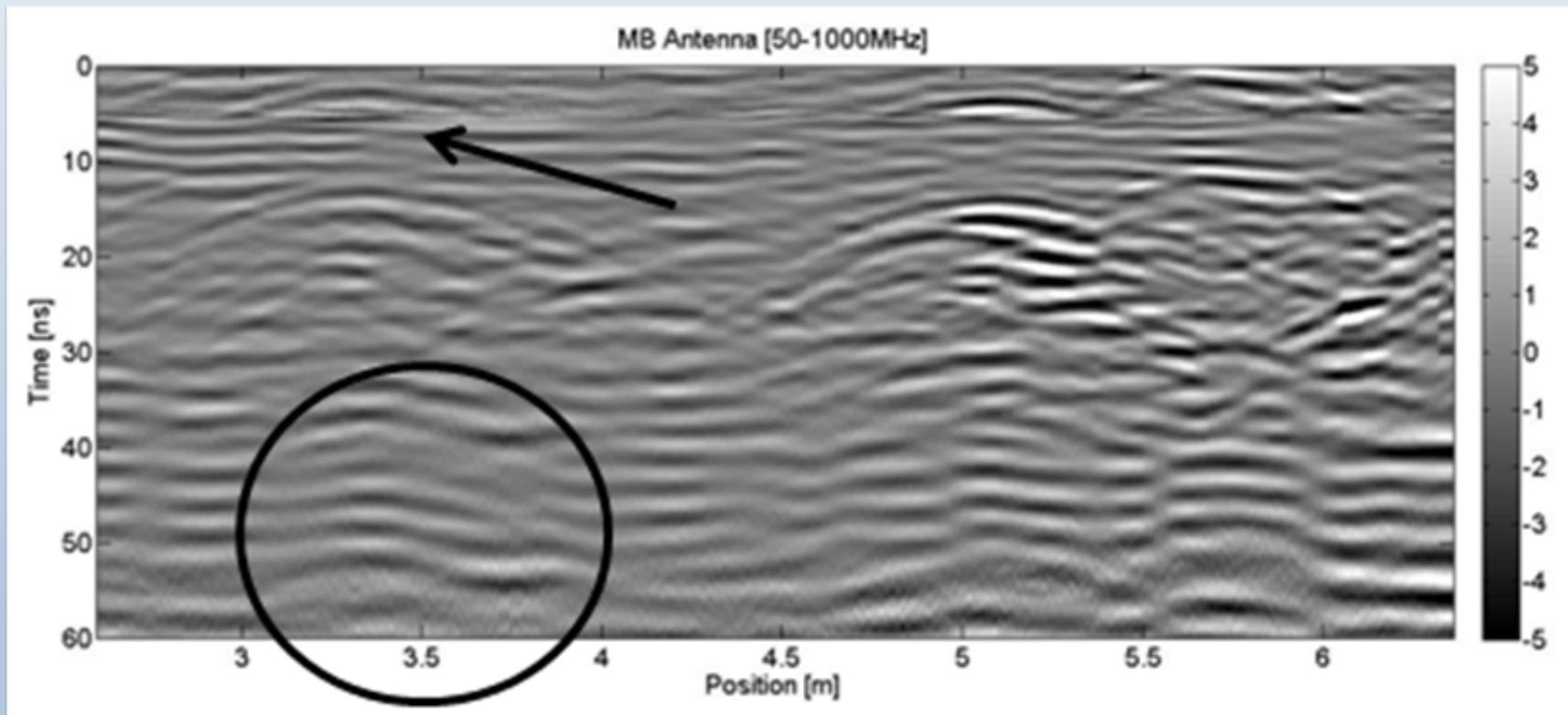
# Interference of the transceivers



# Signal with the default integration times



# Signal with the reconfigured integration times

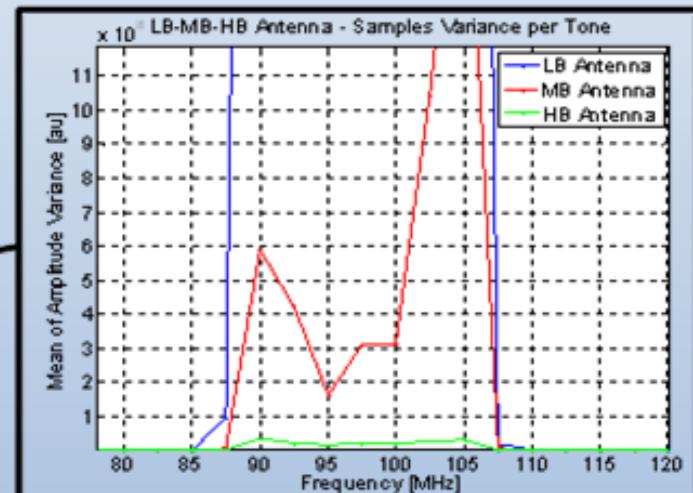
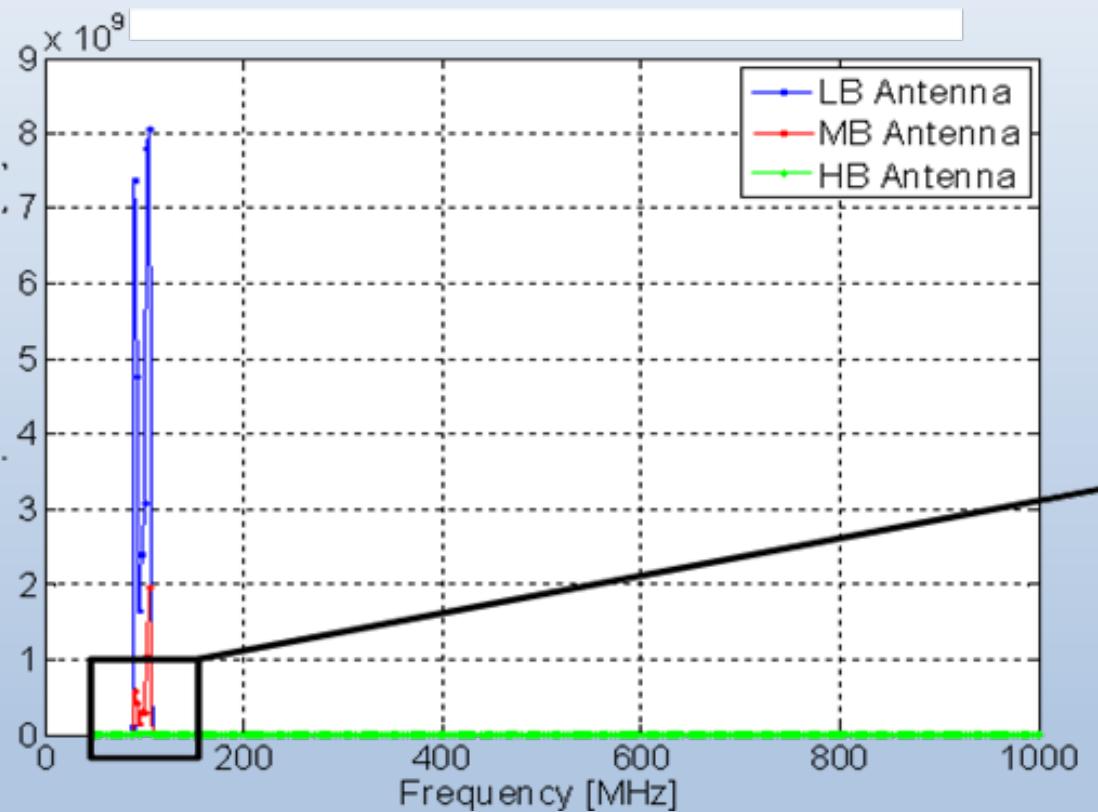


# An experiment in the field

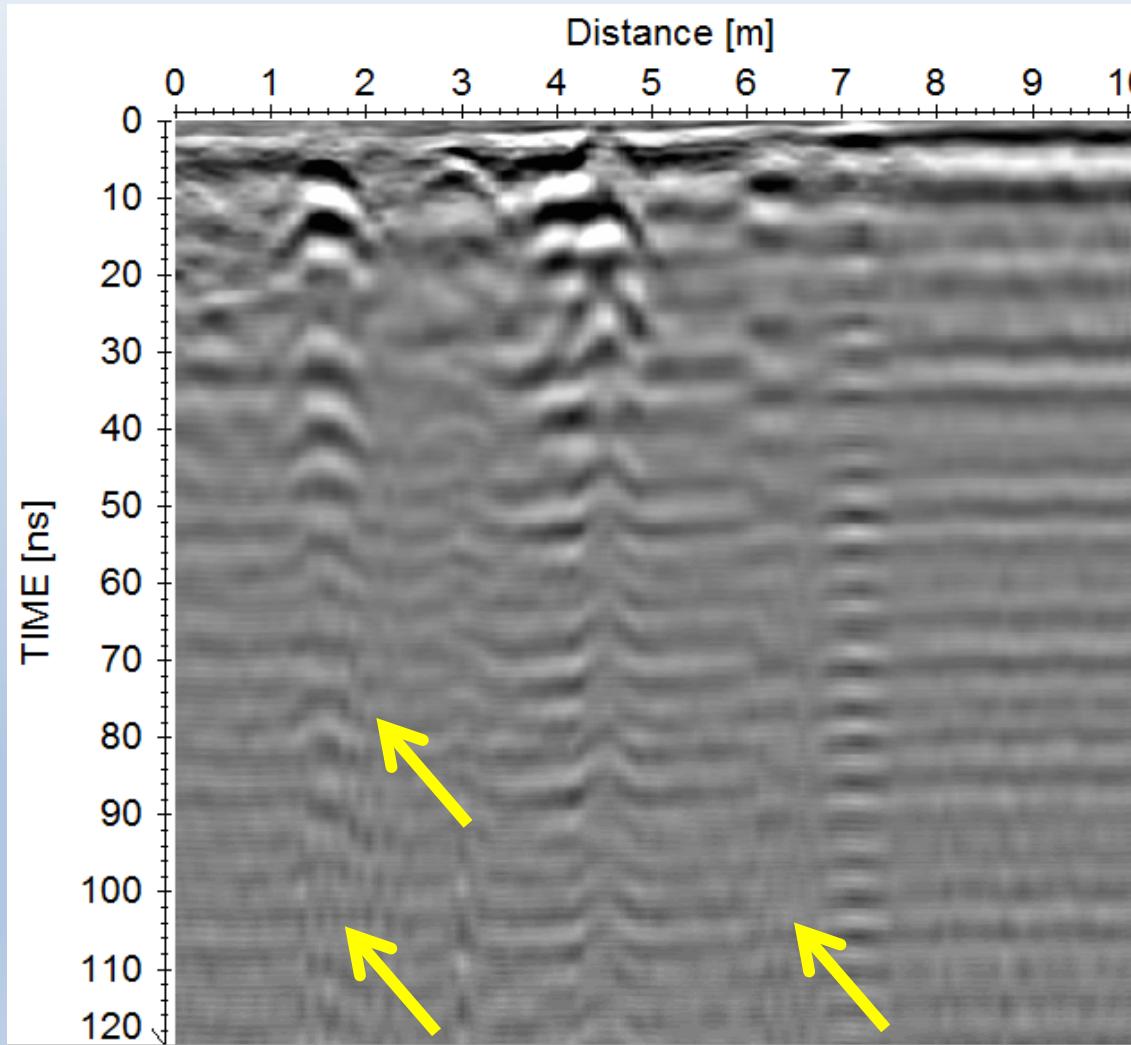


# Interference of the repeater

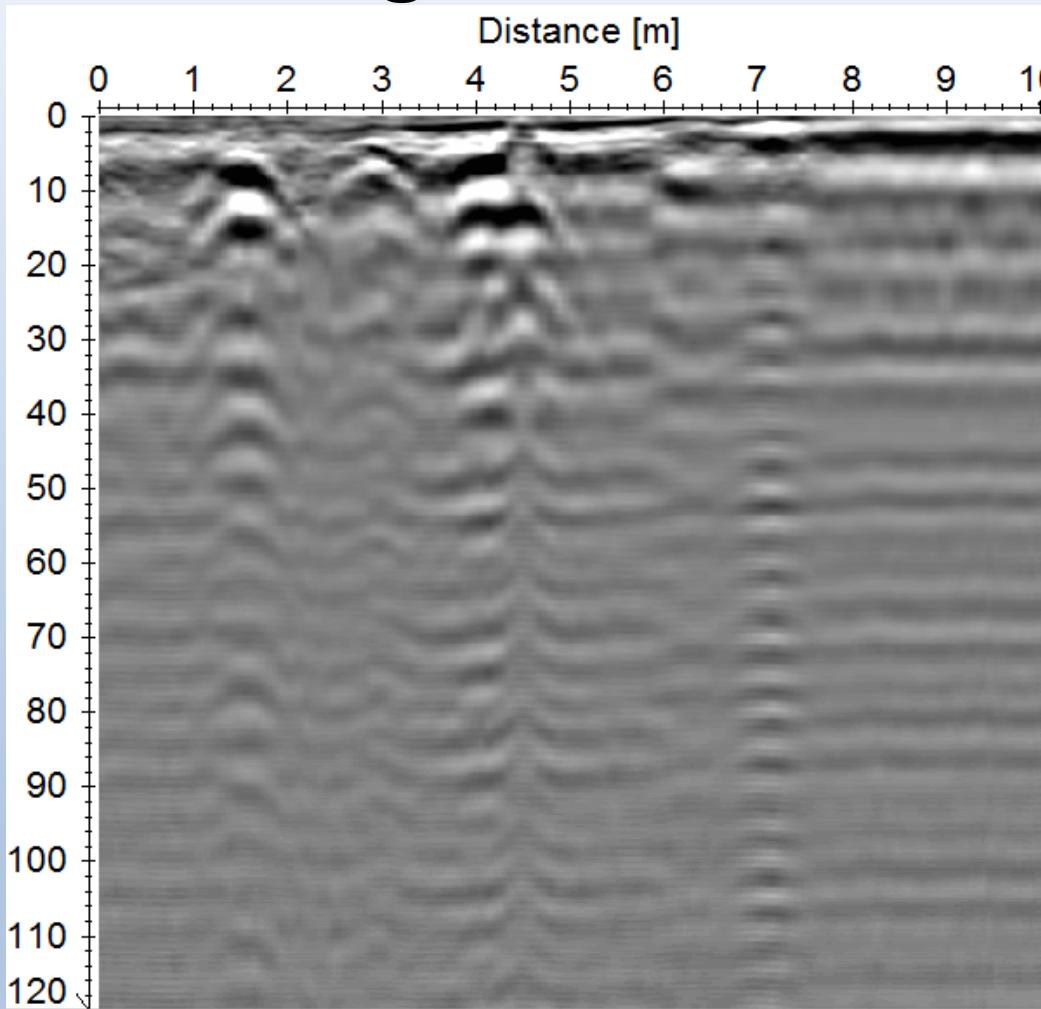
VI



# Signal with the default integration times



# Signal with the reconfigured integration times



*Increasing of the comprehensive measurement time less than 5% in both cases.*